

FIGURE 3

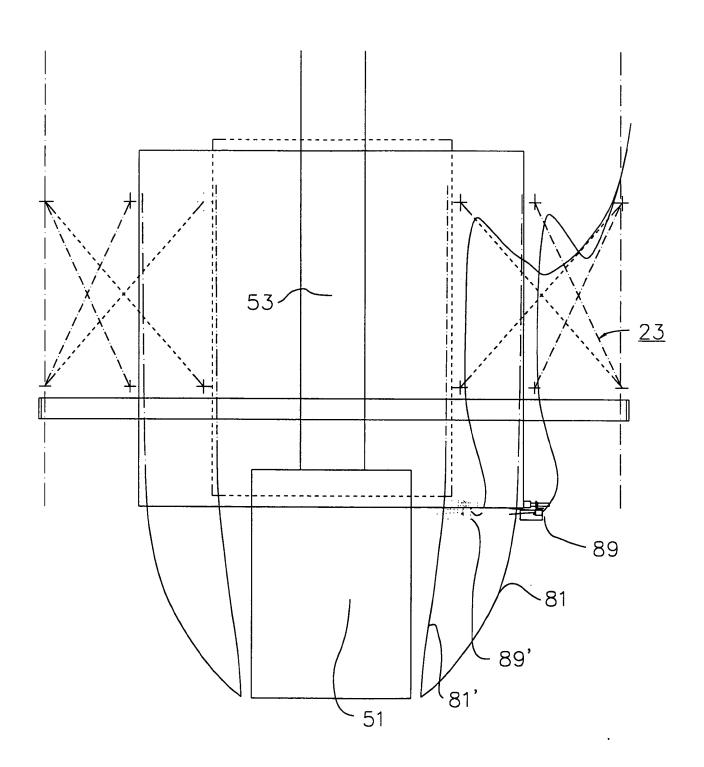
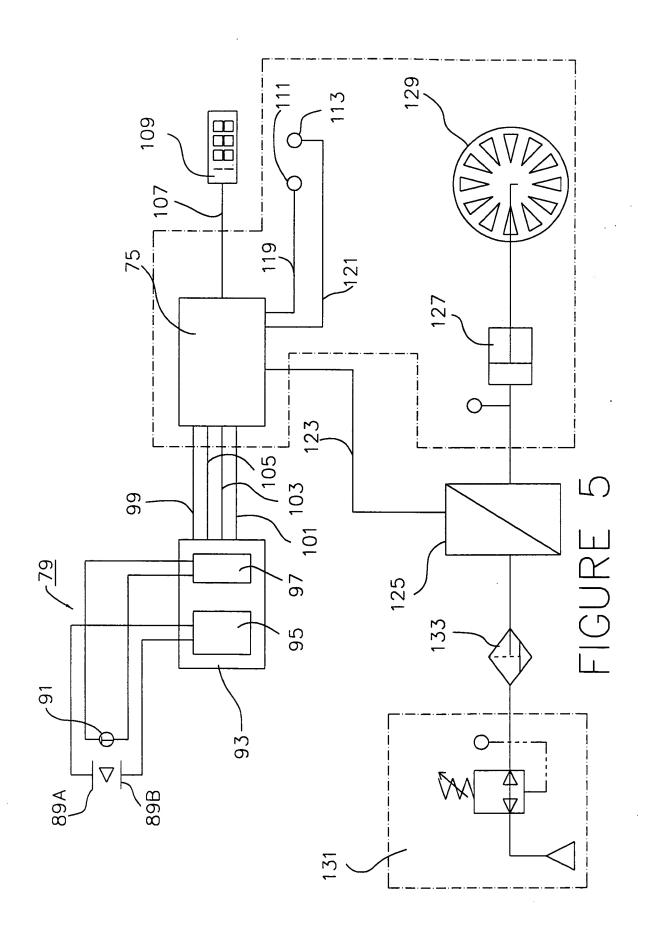
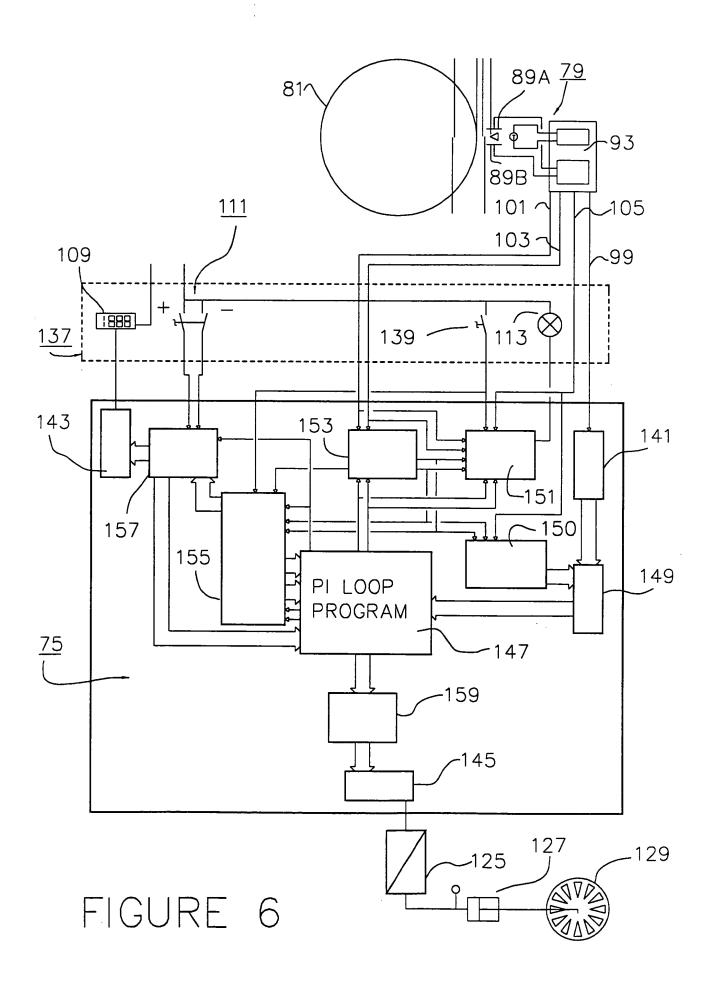


FIGURE 4





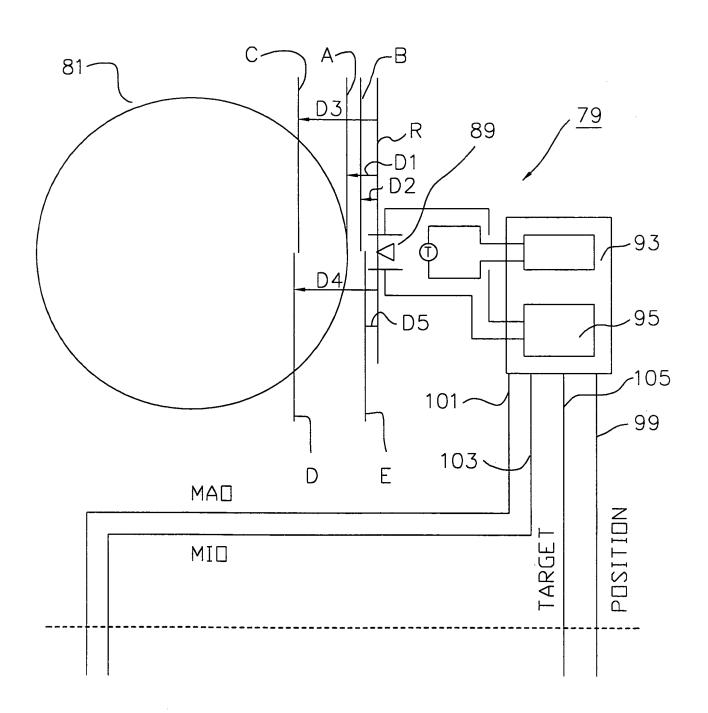
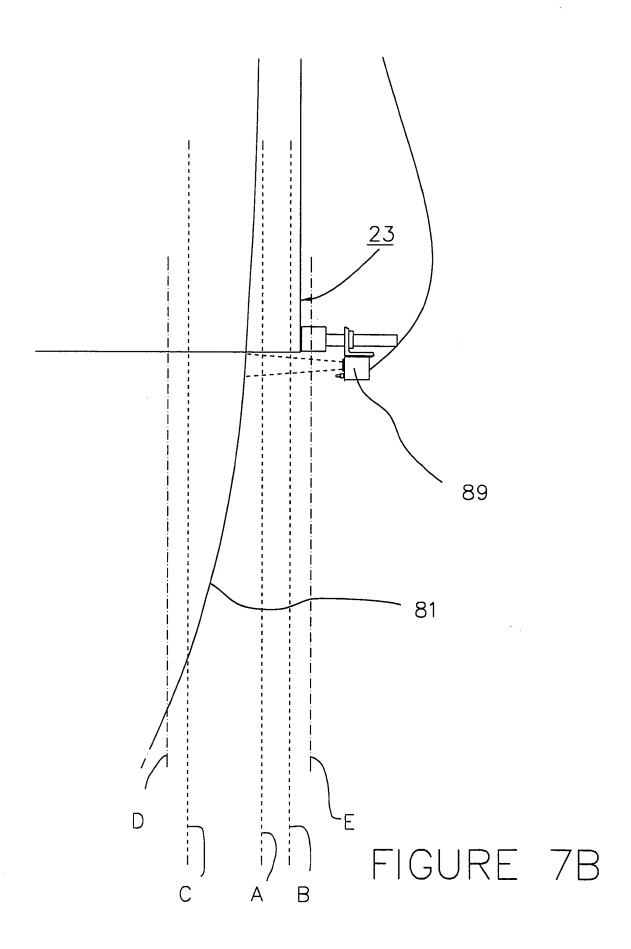


FIGURE 7A



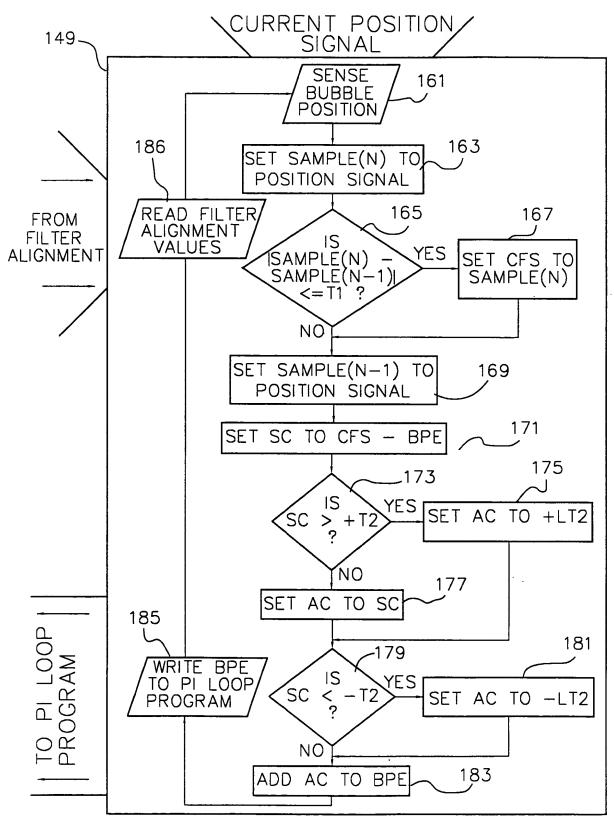
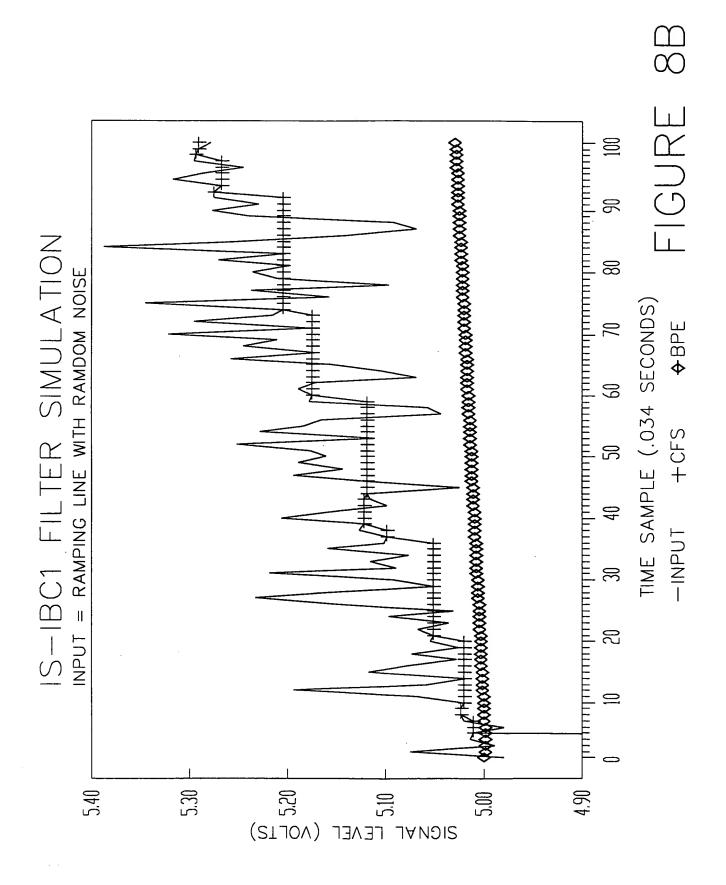


FIGURE 8A



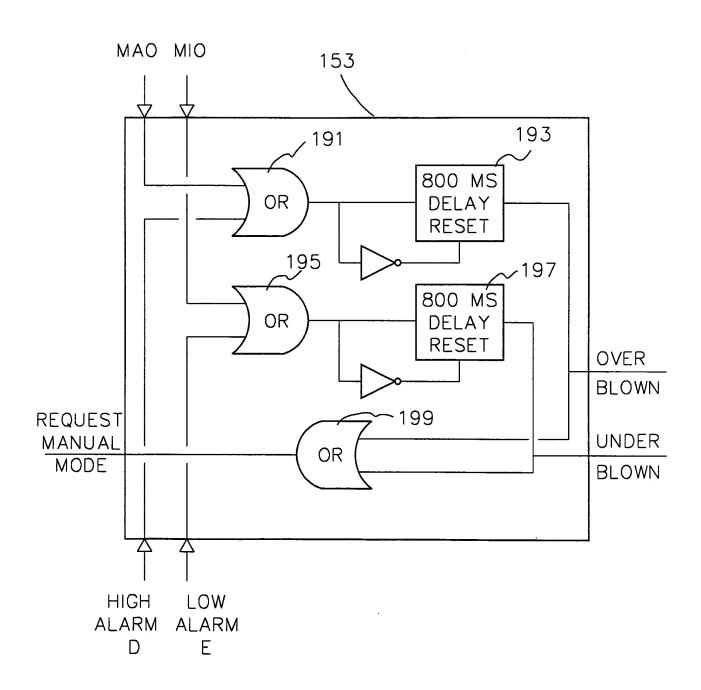
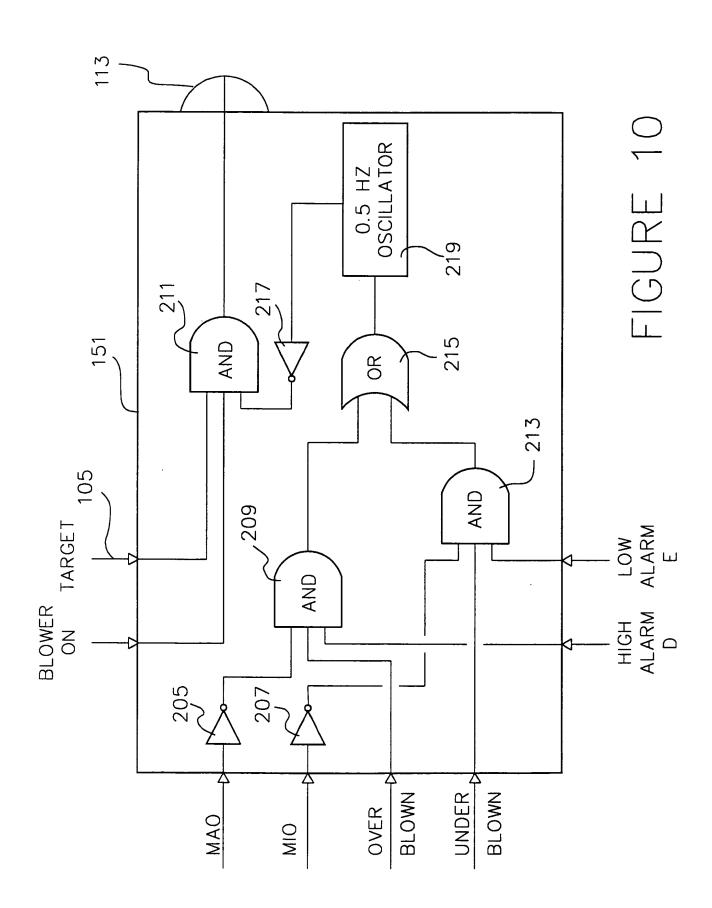
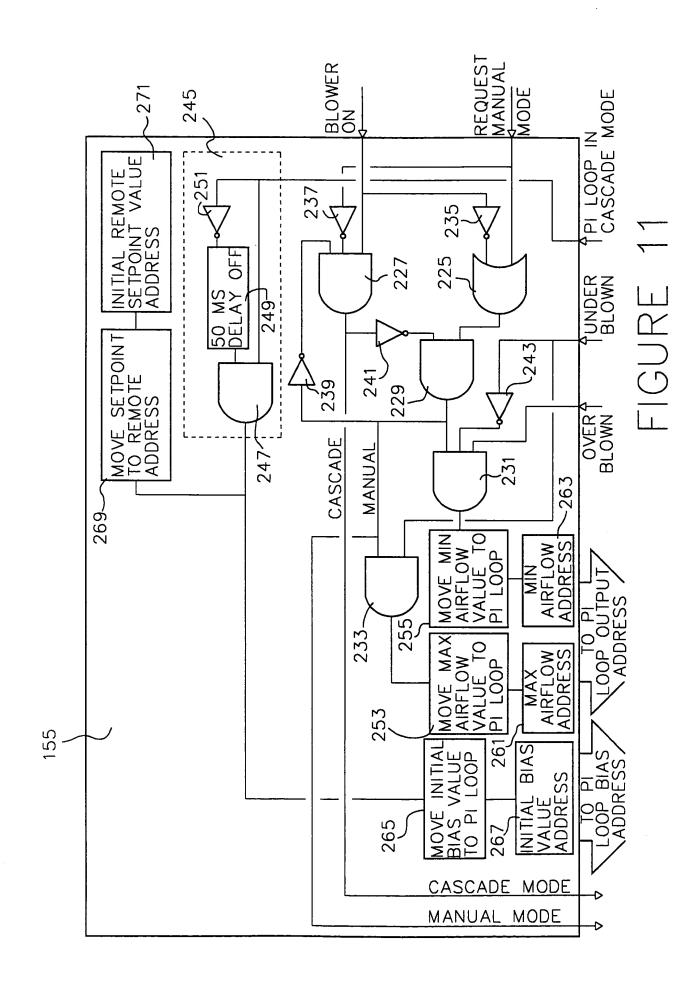
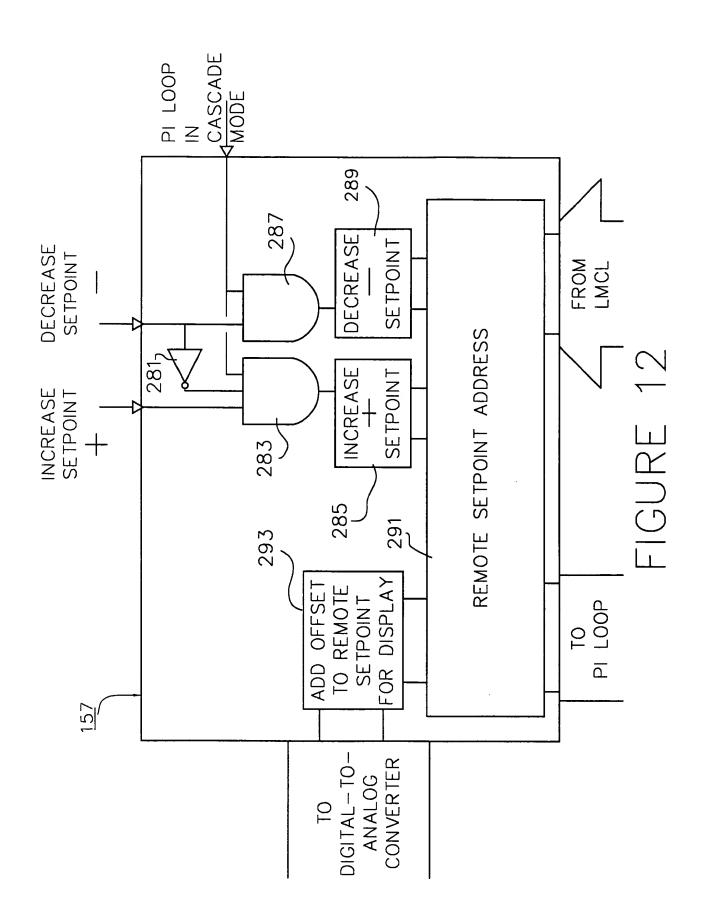
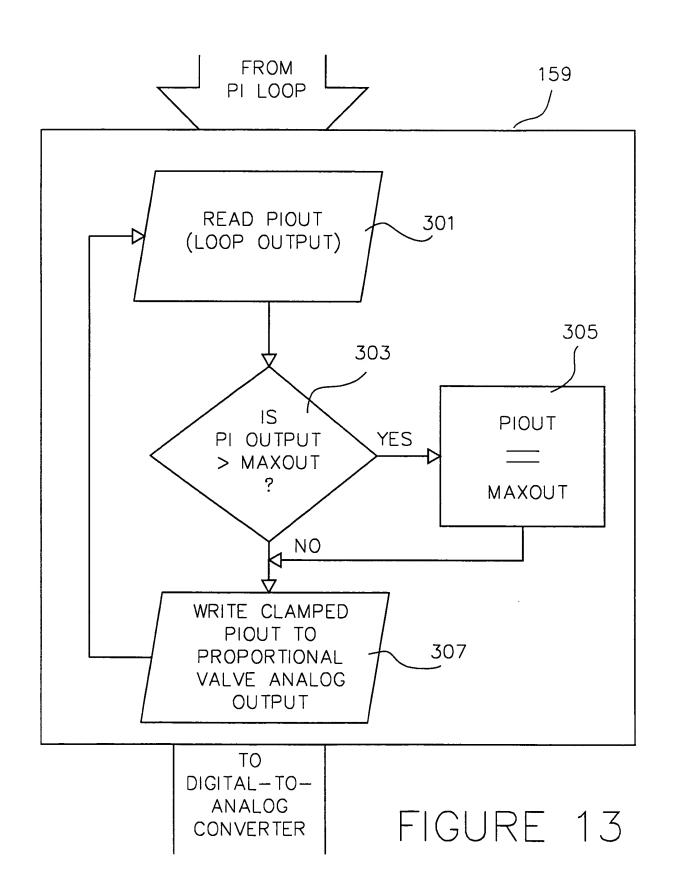


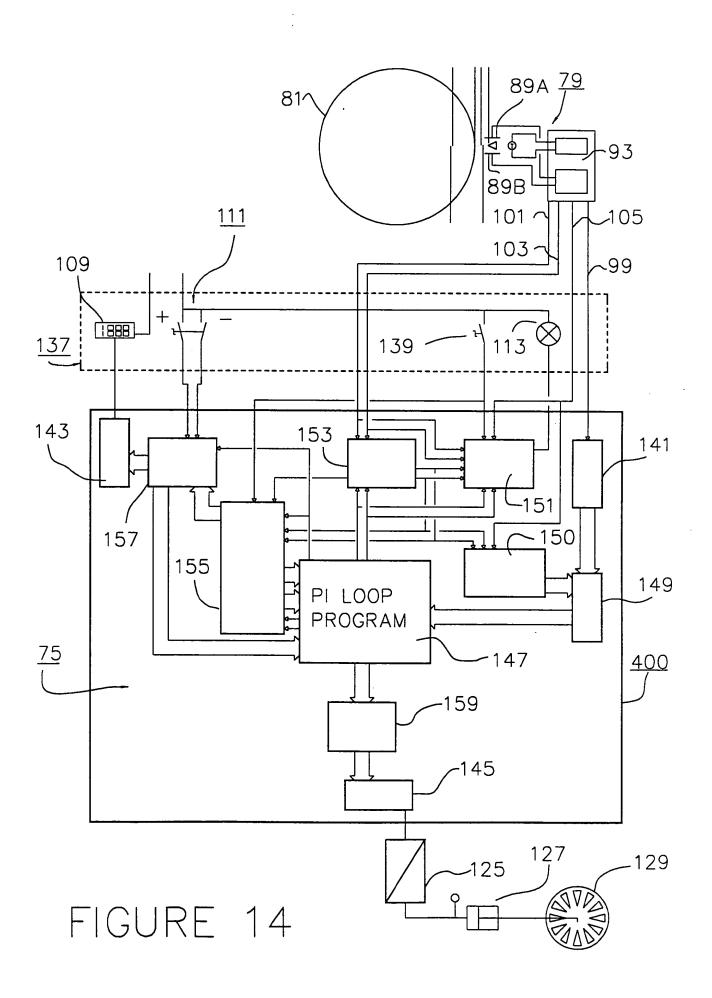
FIGURE 9











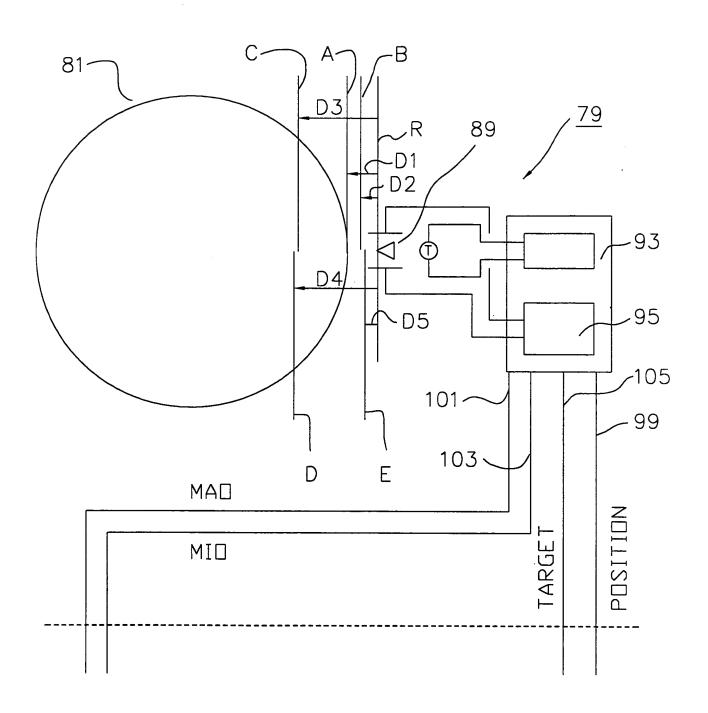
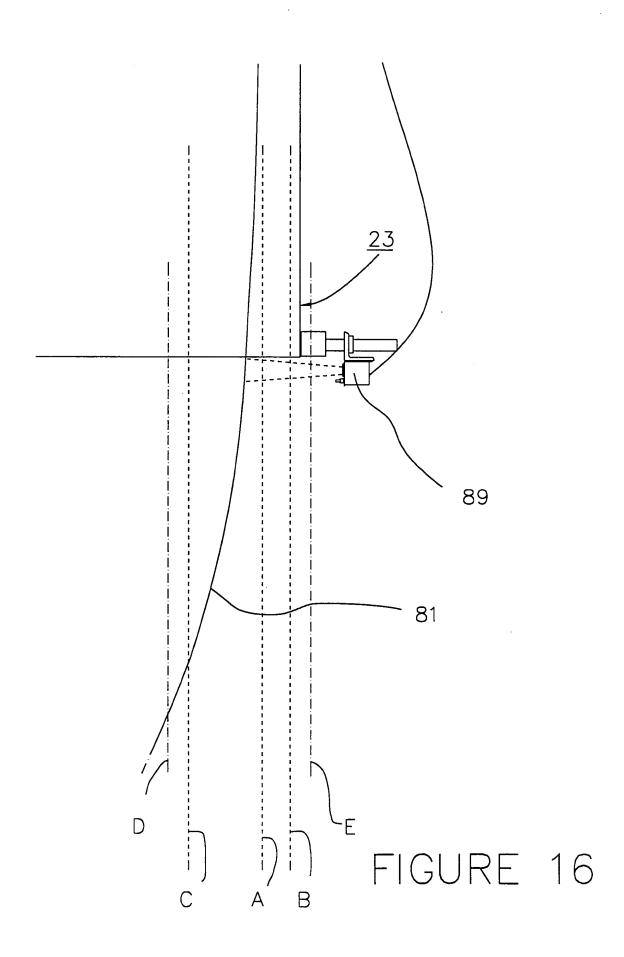


FIGURE 15



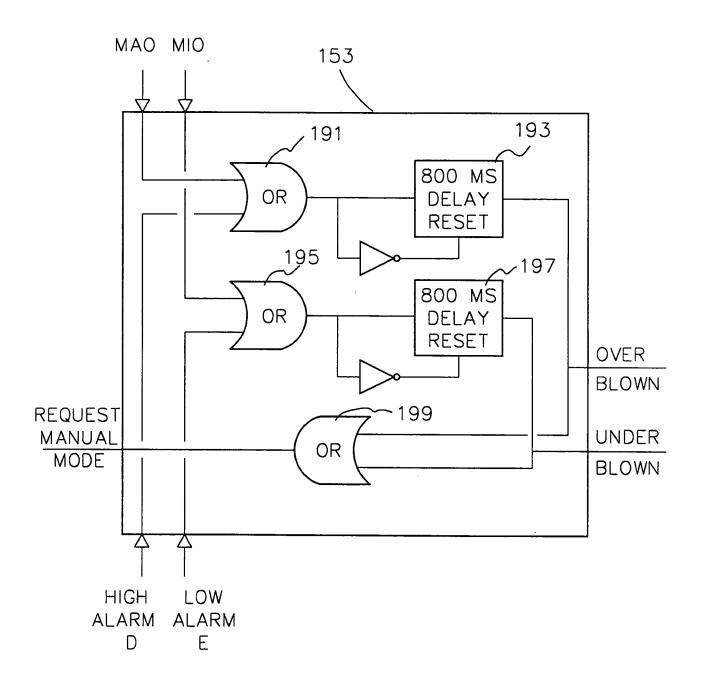
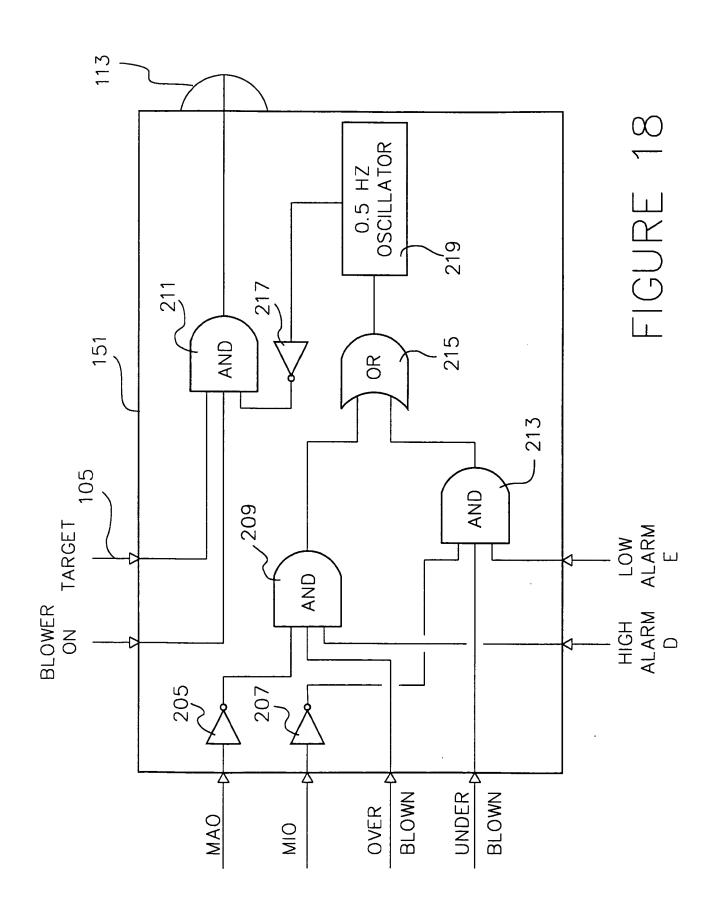
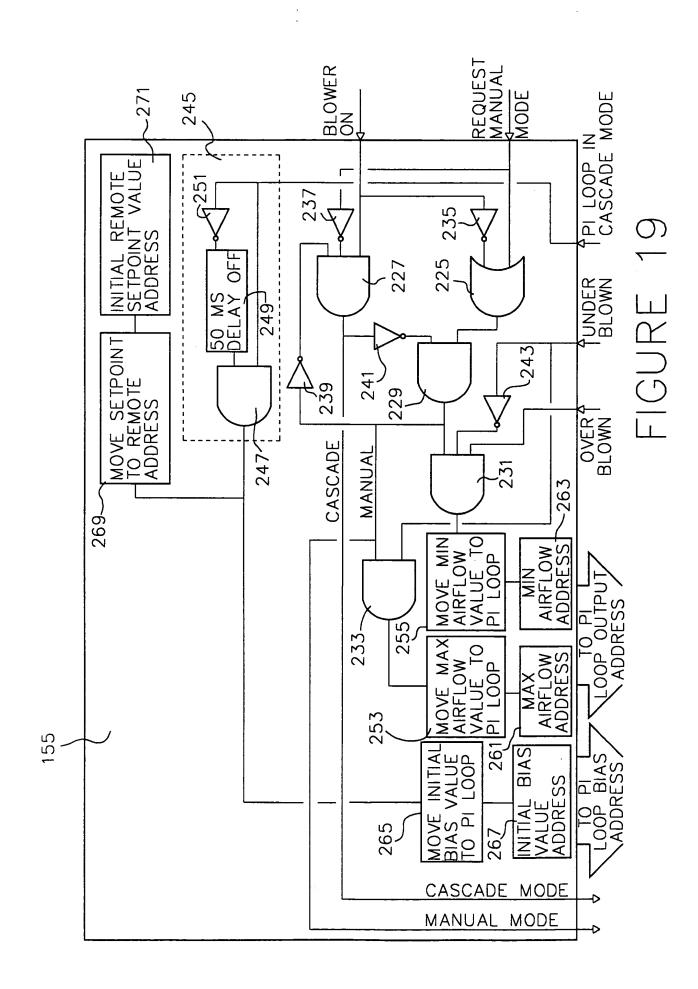
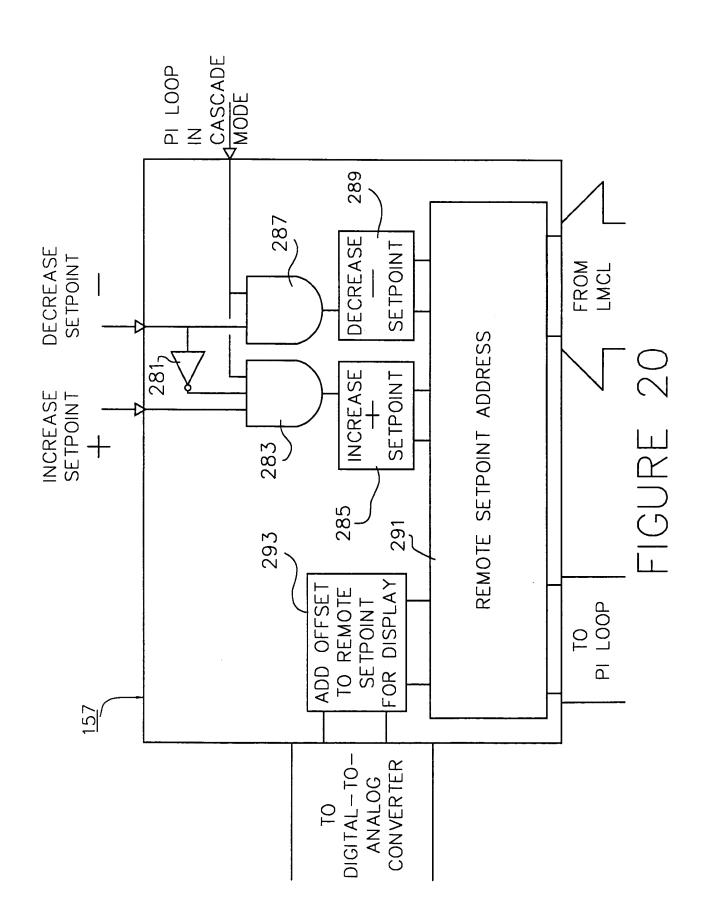
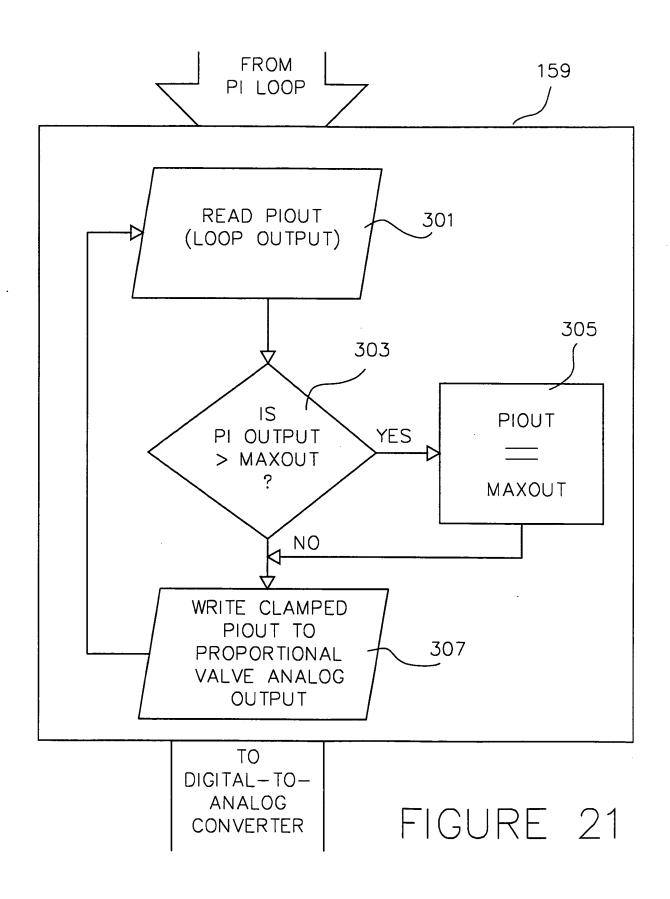


FIGURE 17









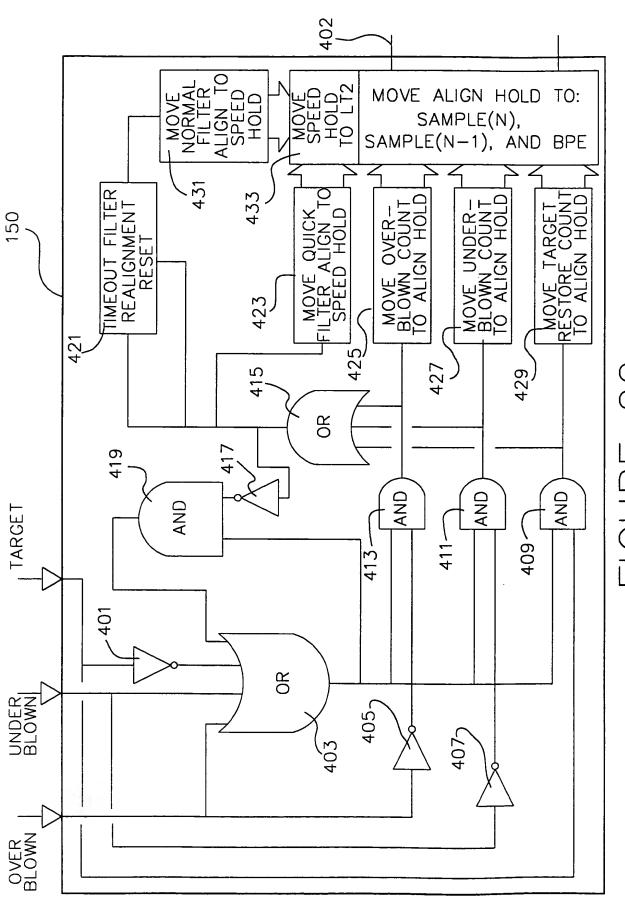
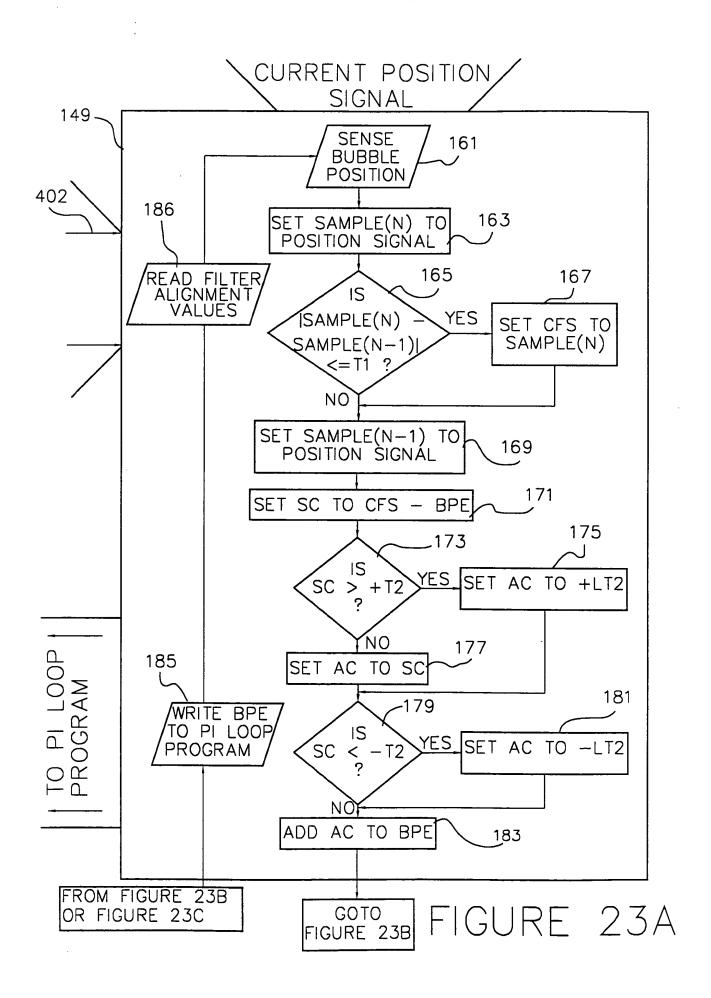
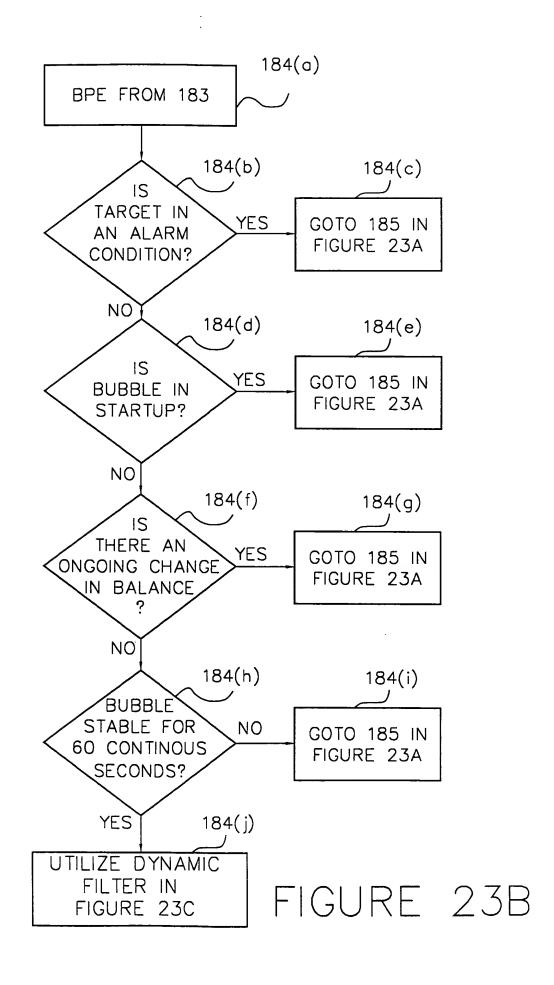
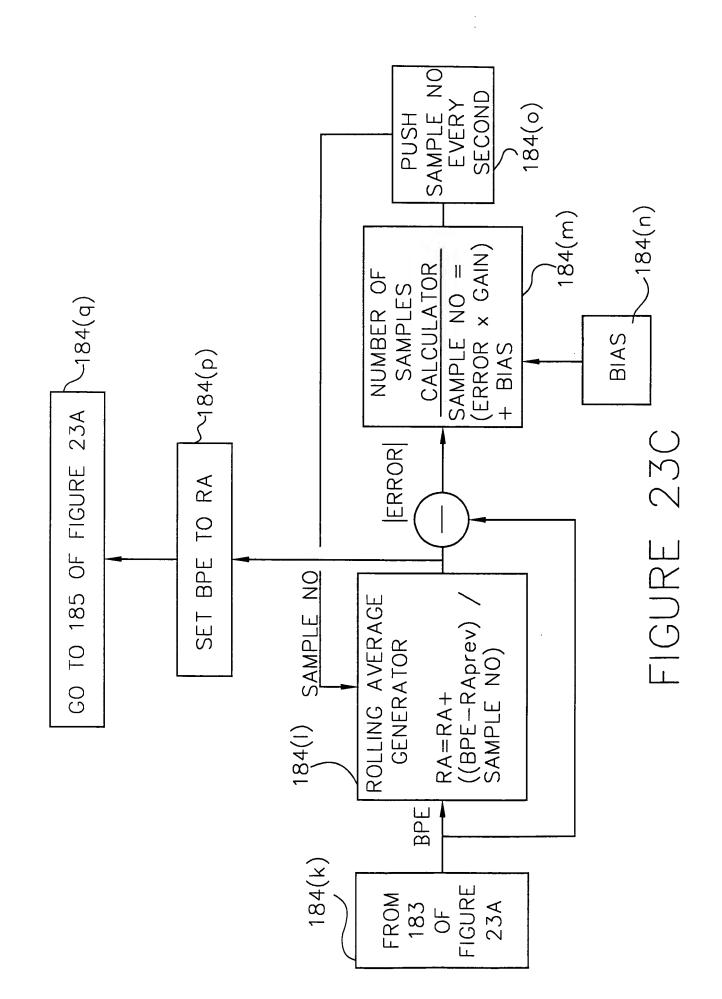
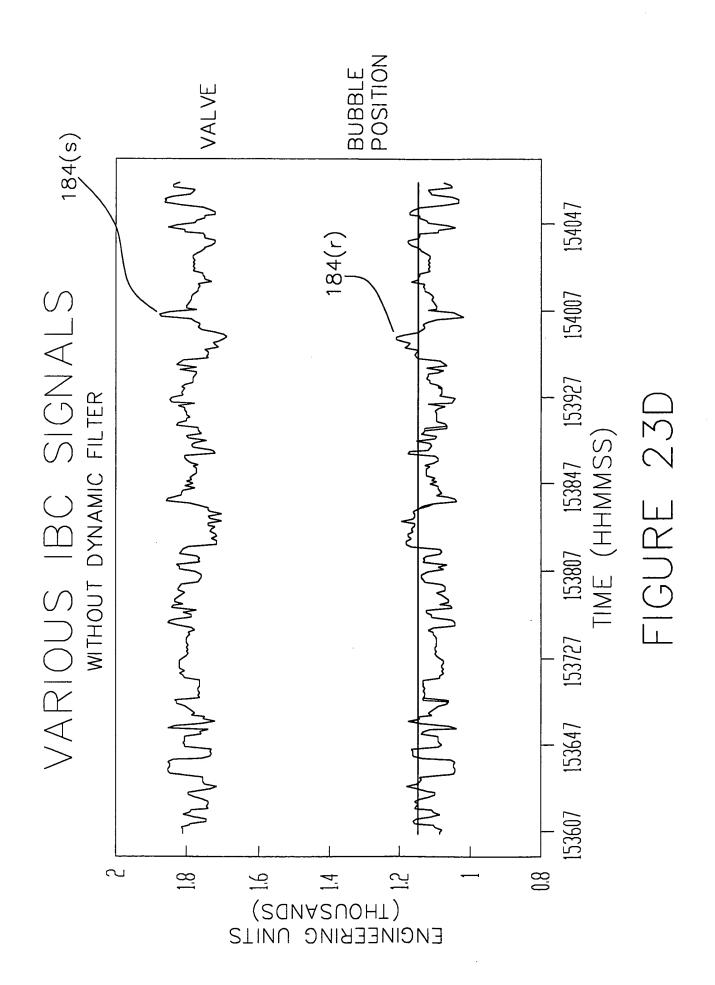


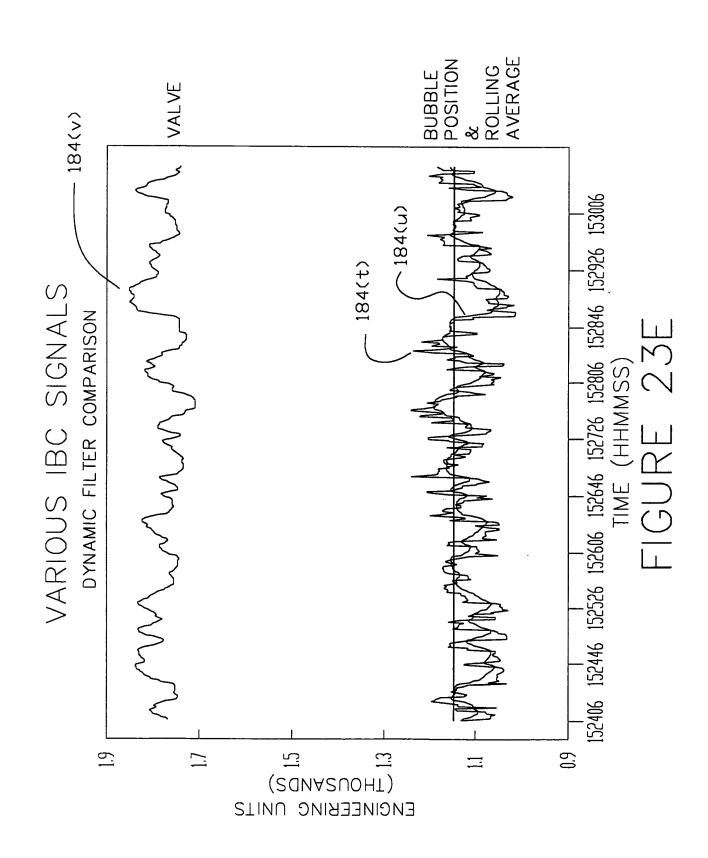
FIGURE 22

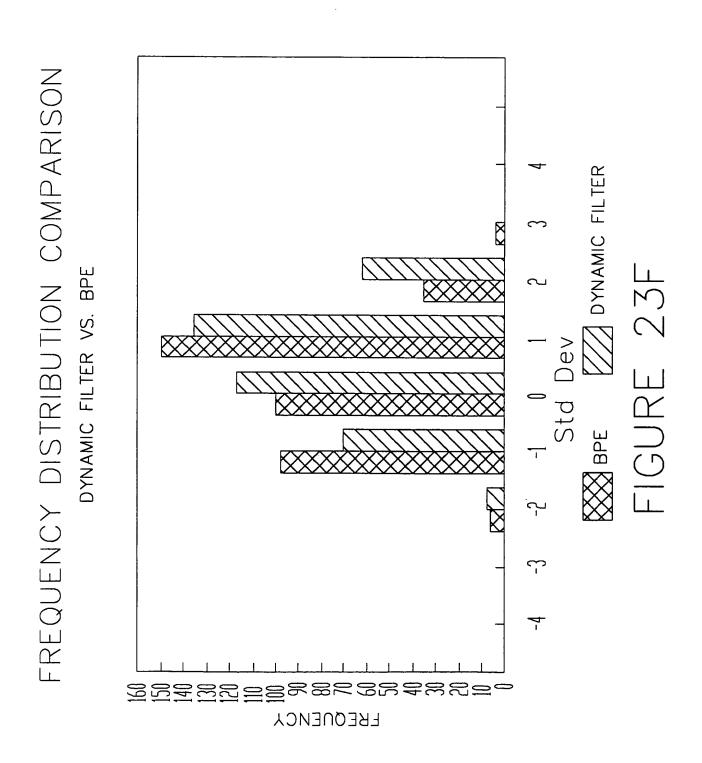


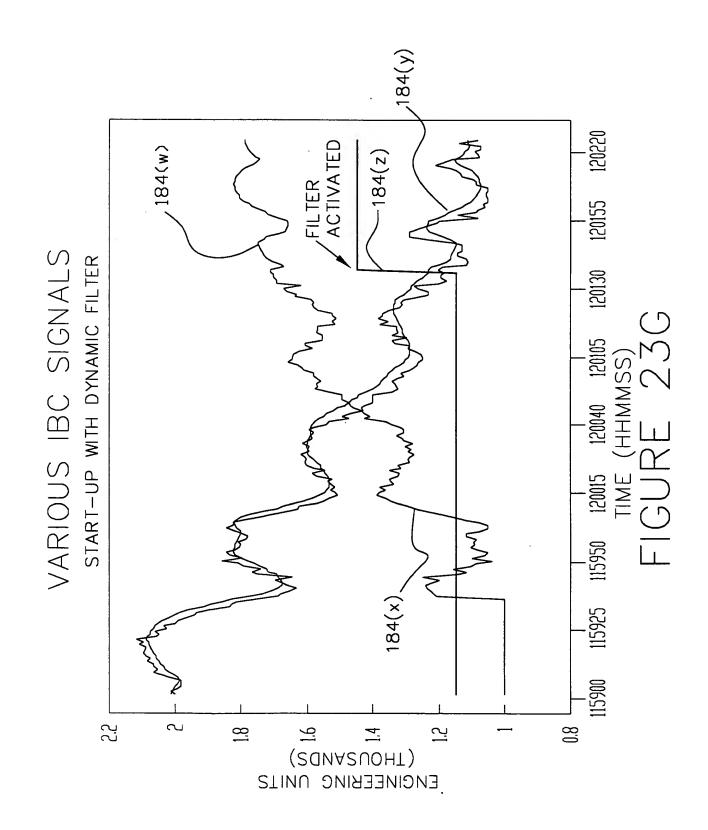


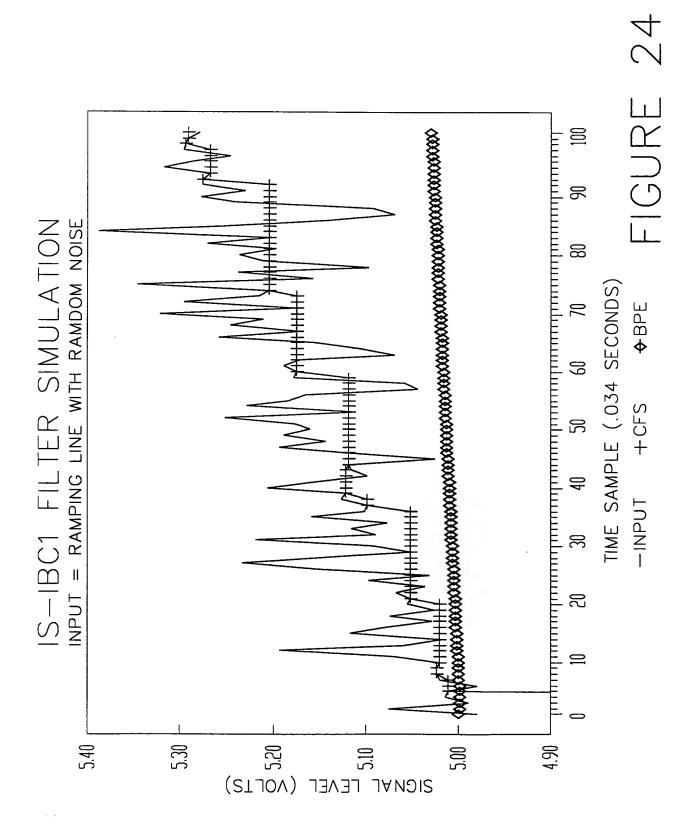




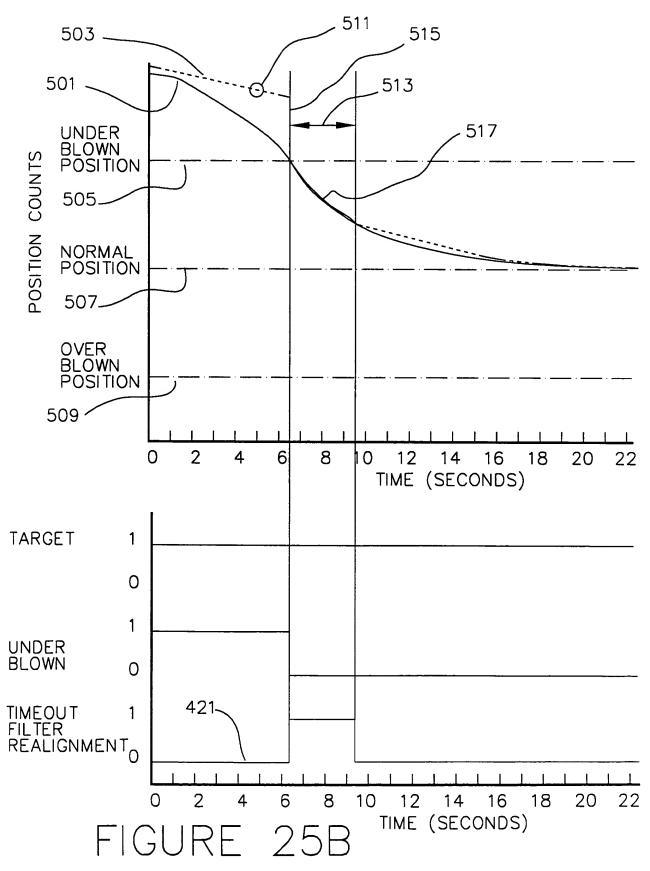


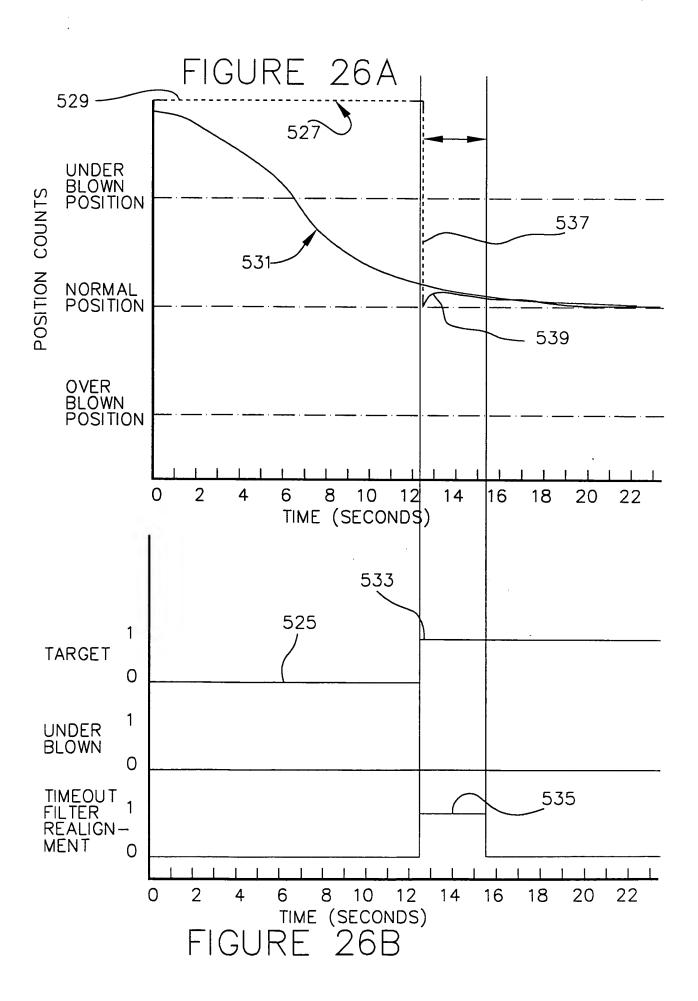












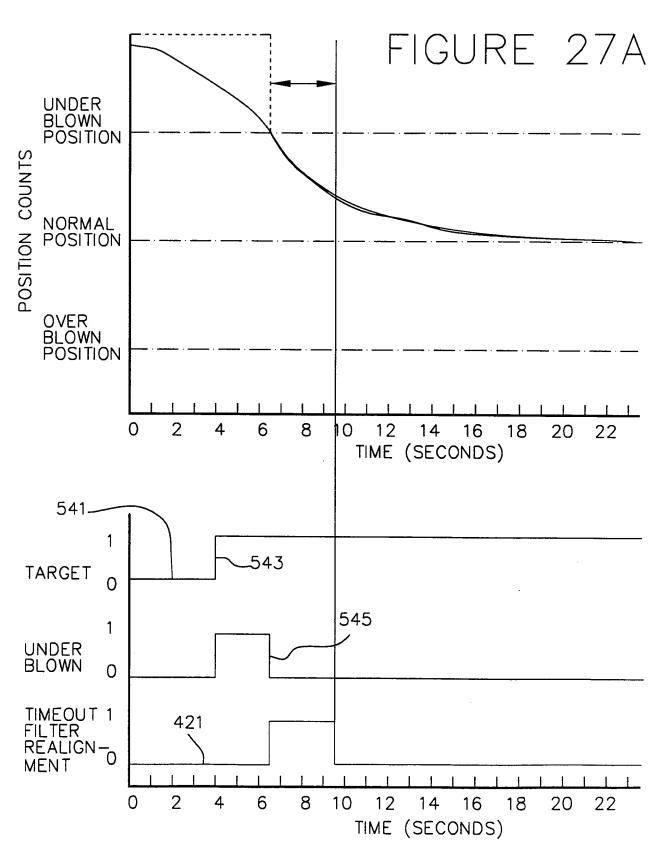
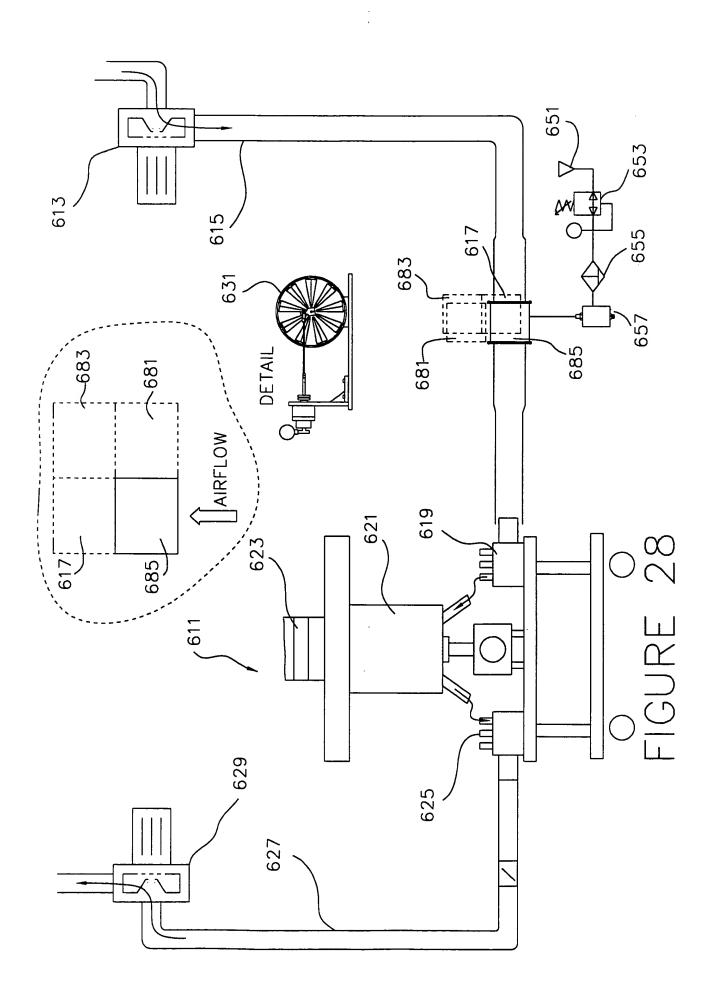
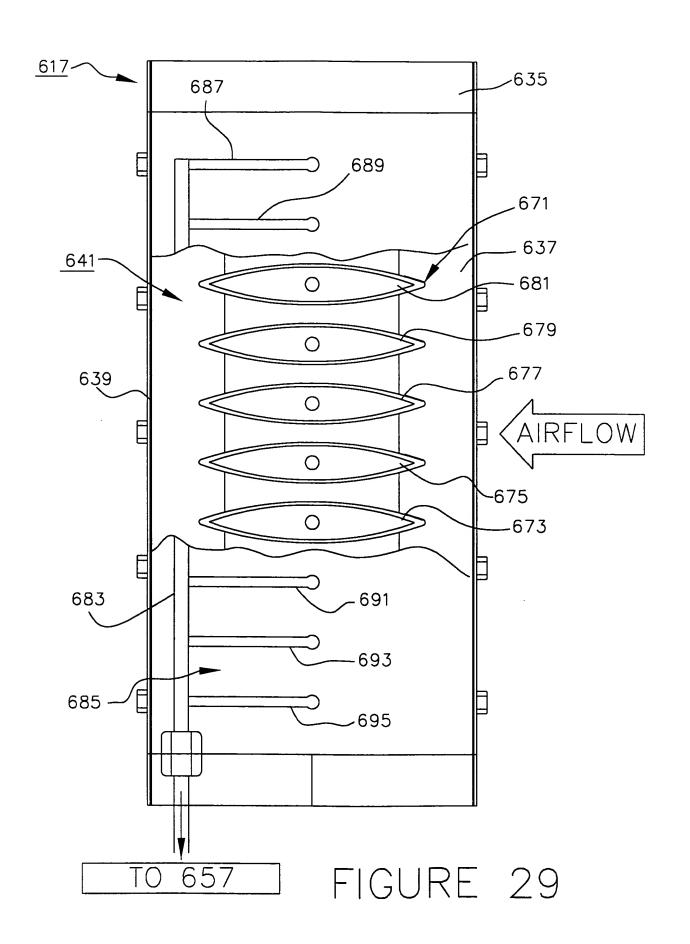
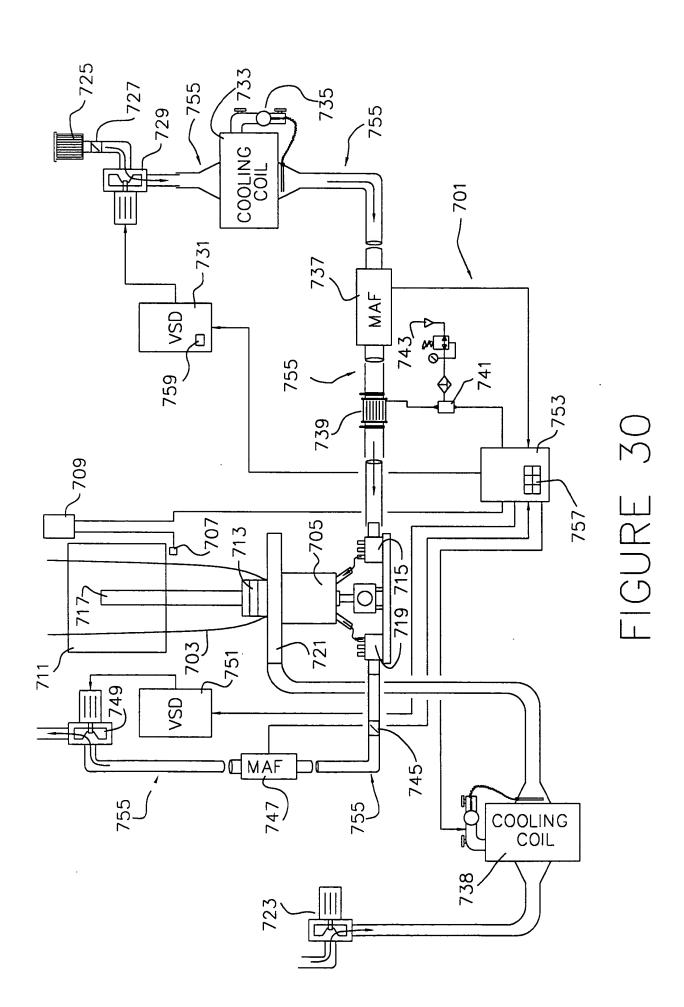
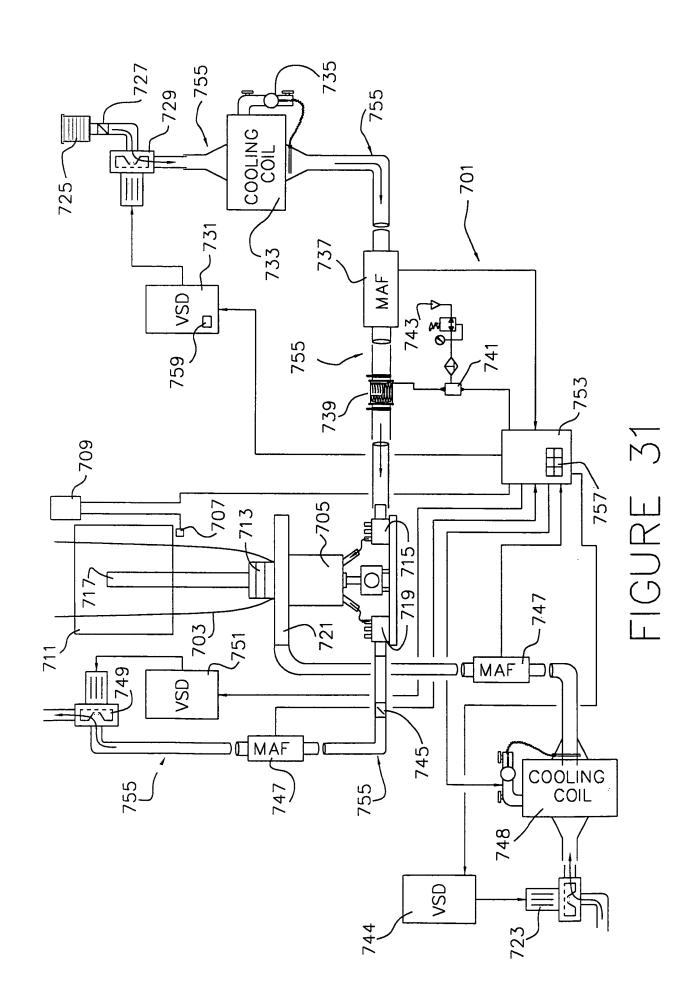


FIGURE 27B









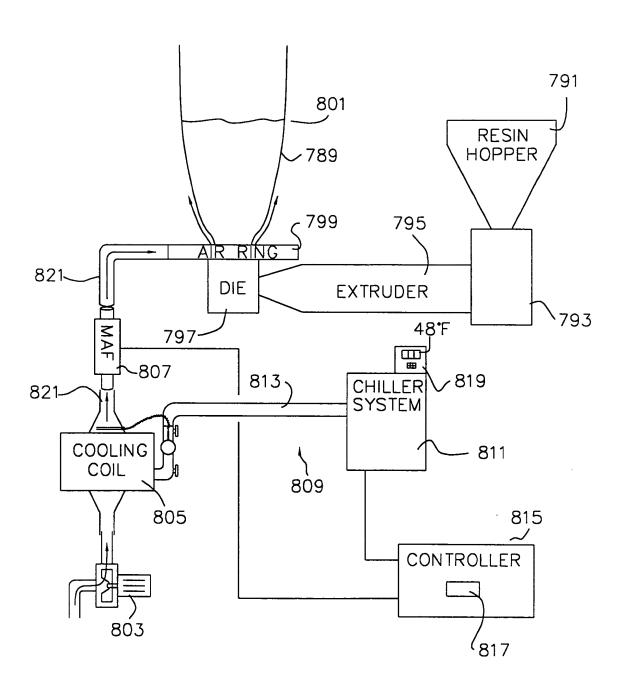


FIGURE 32

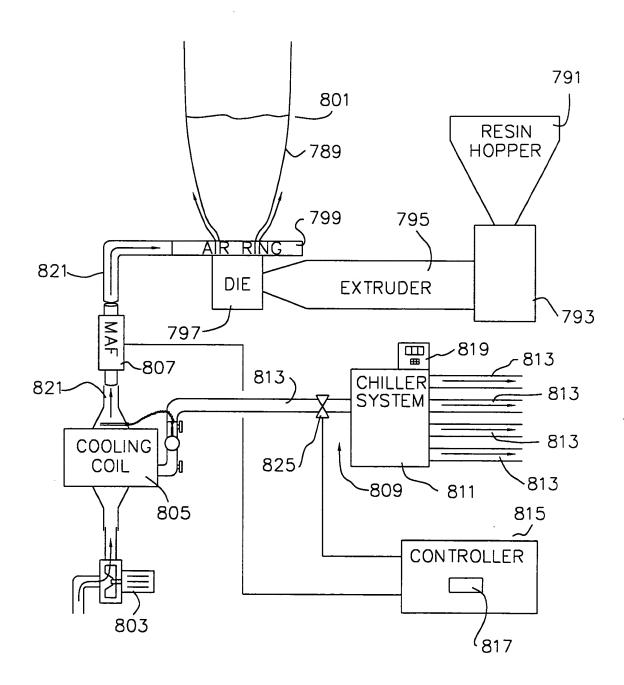


FIGURE 33

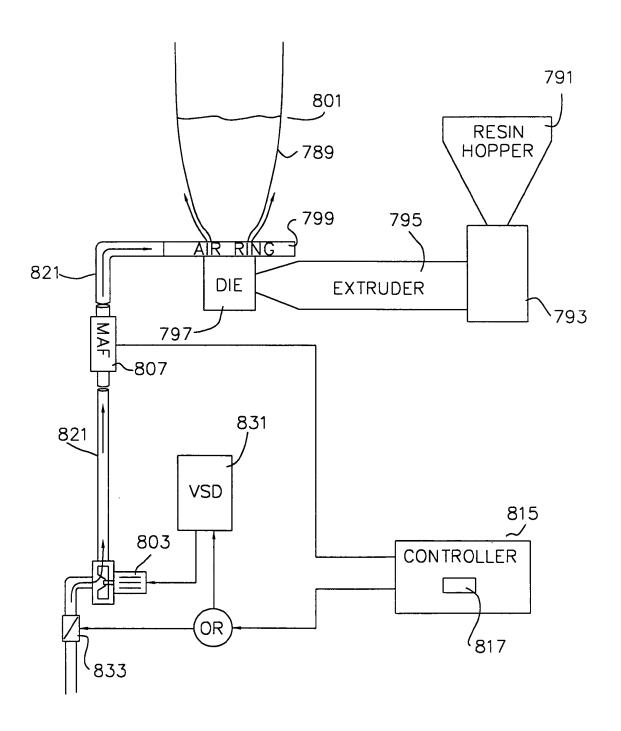


FIGURE 34

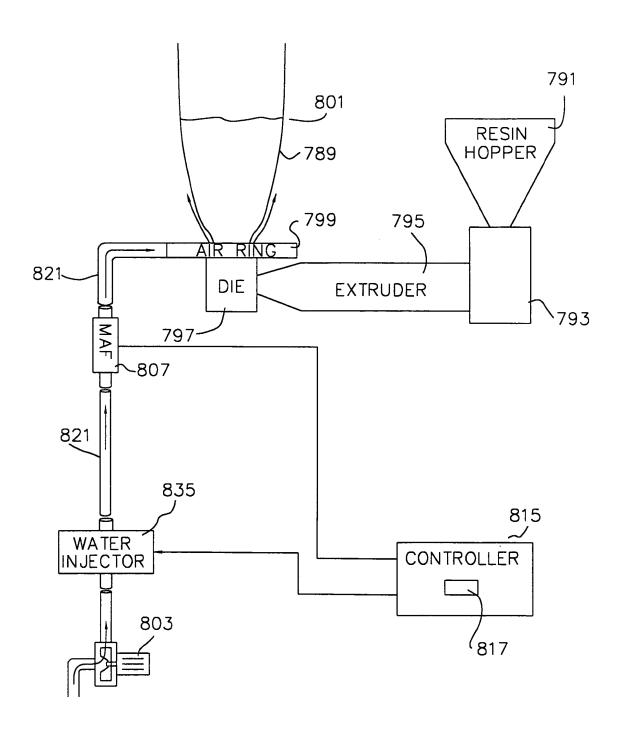
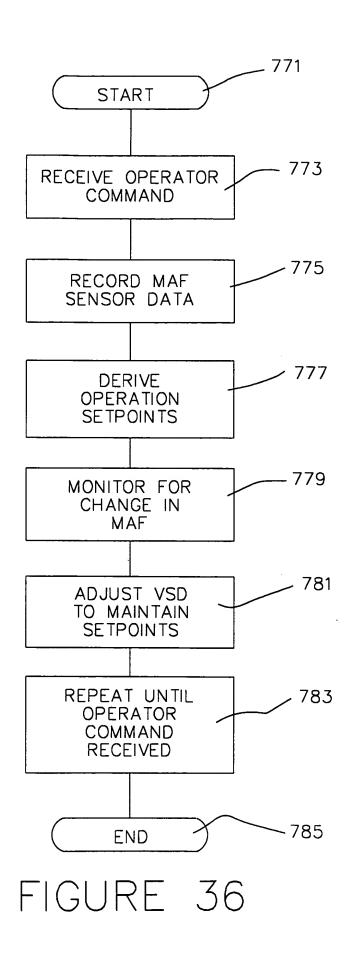
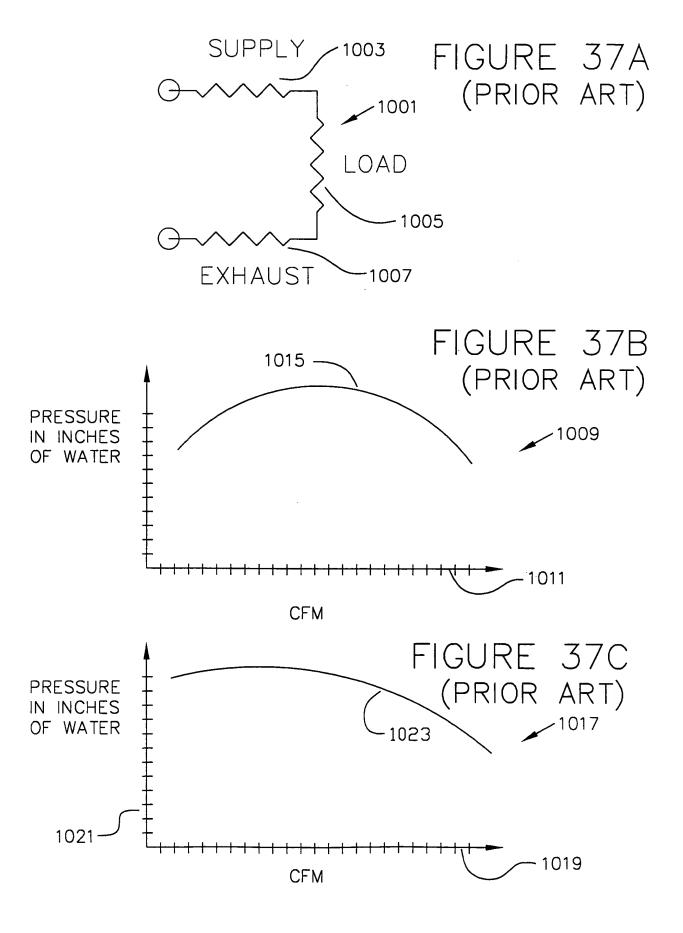


FIGURE 35





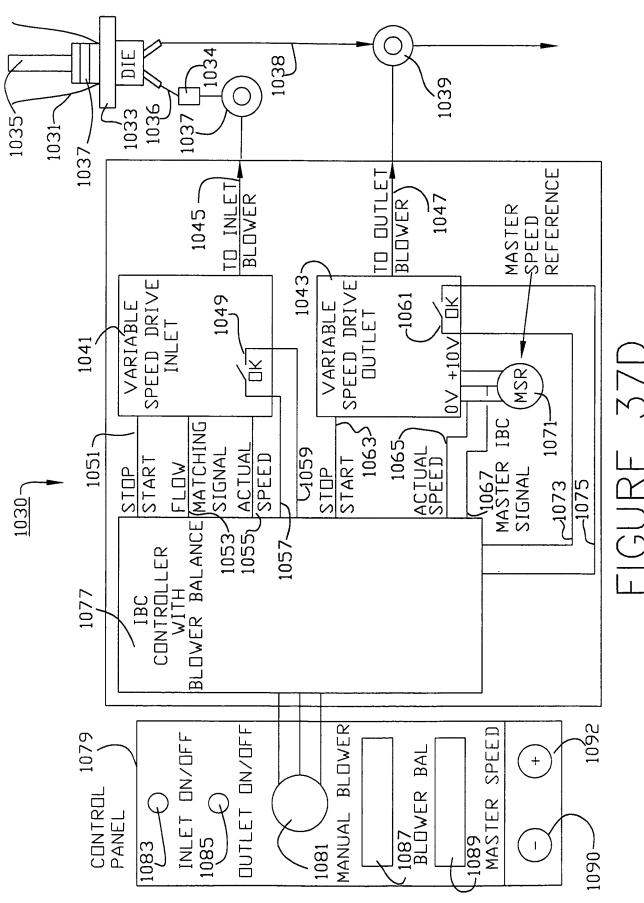


FIGURE 370

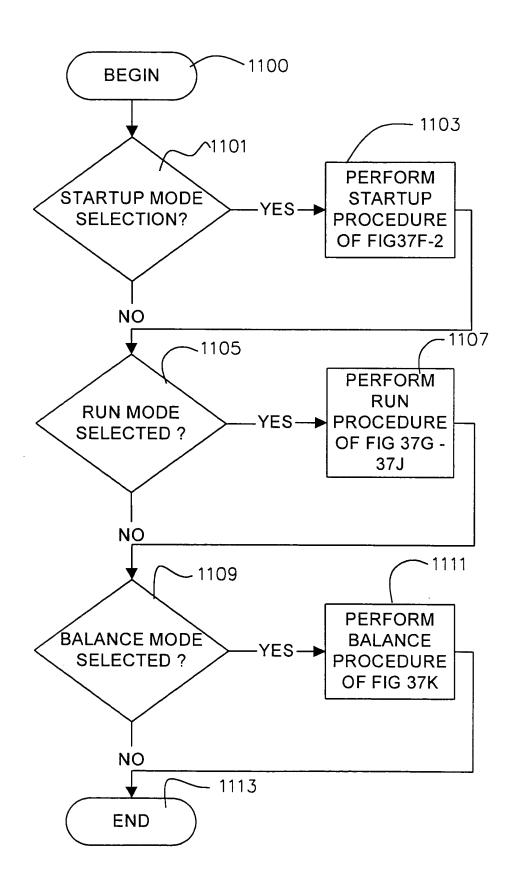
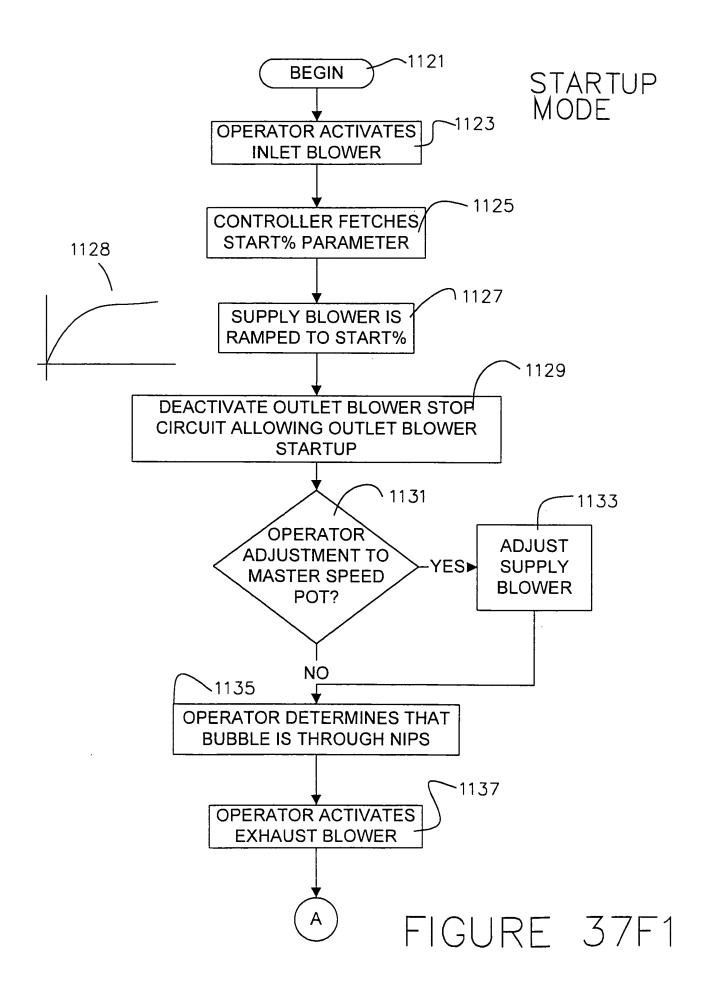
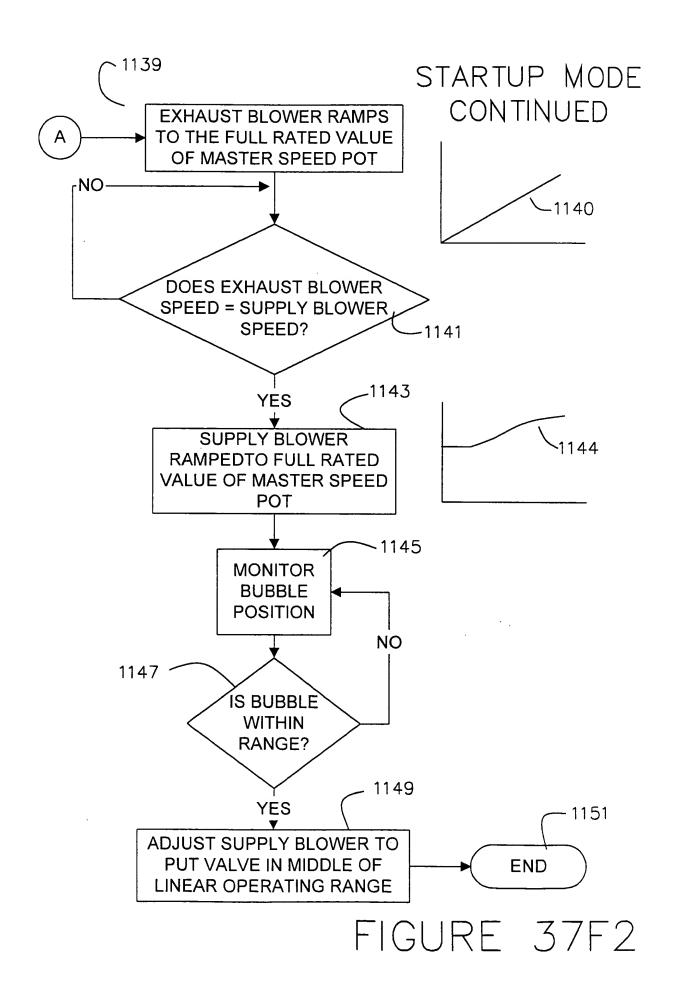
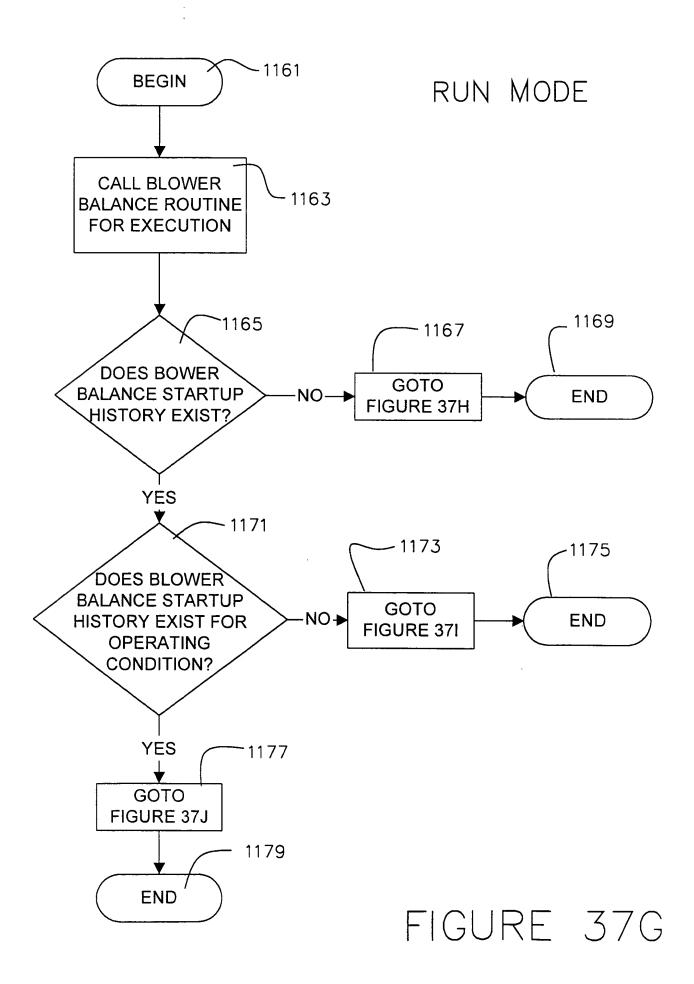
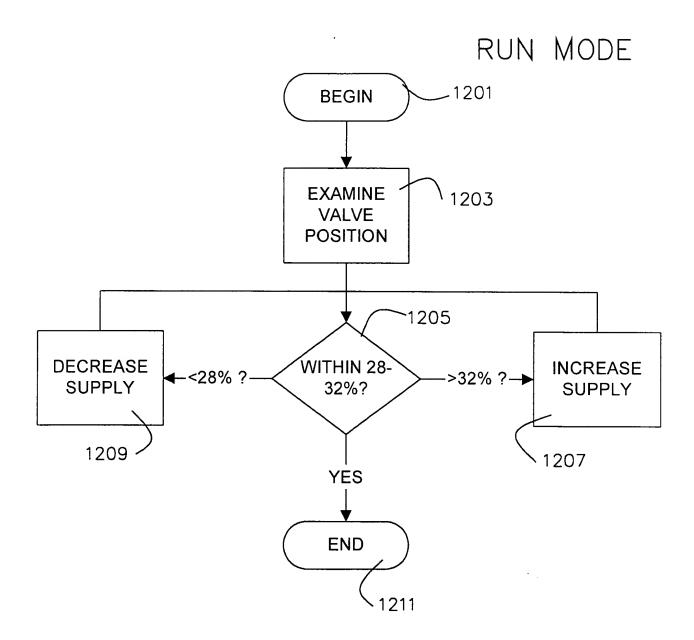


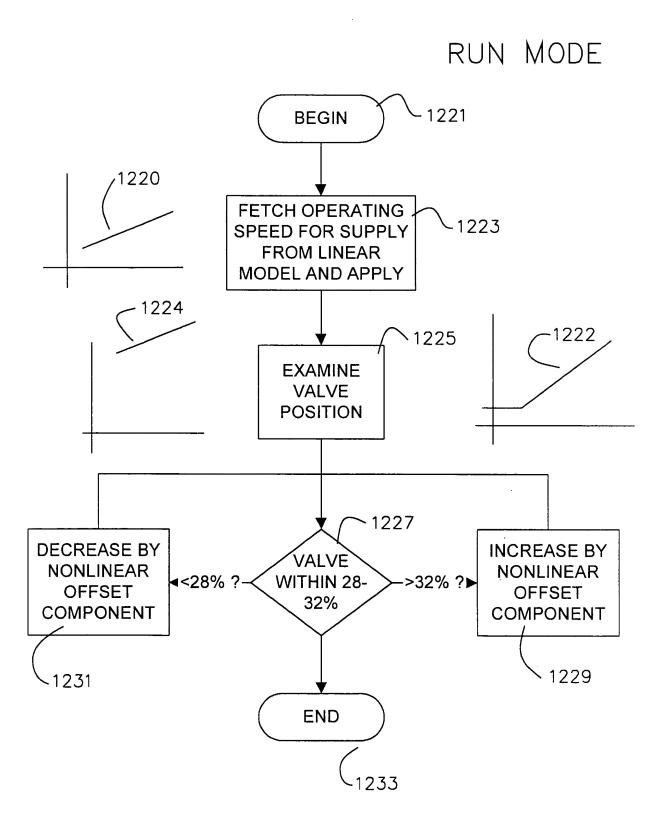
FIGURE 37E

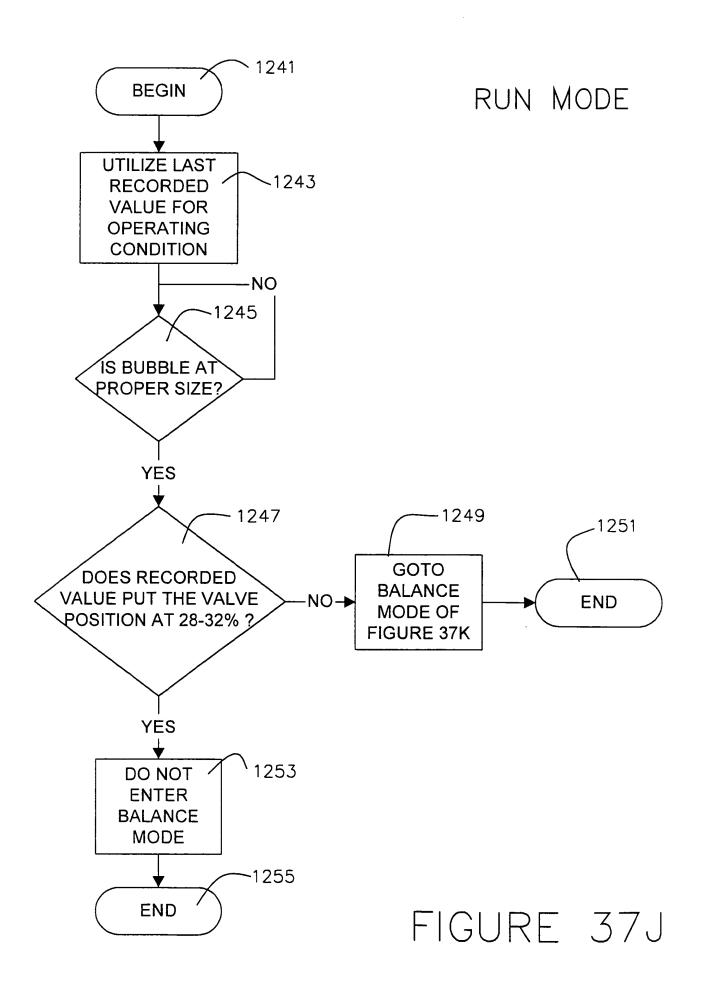


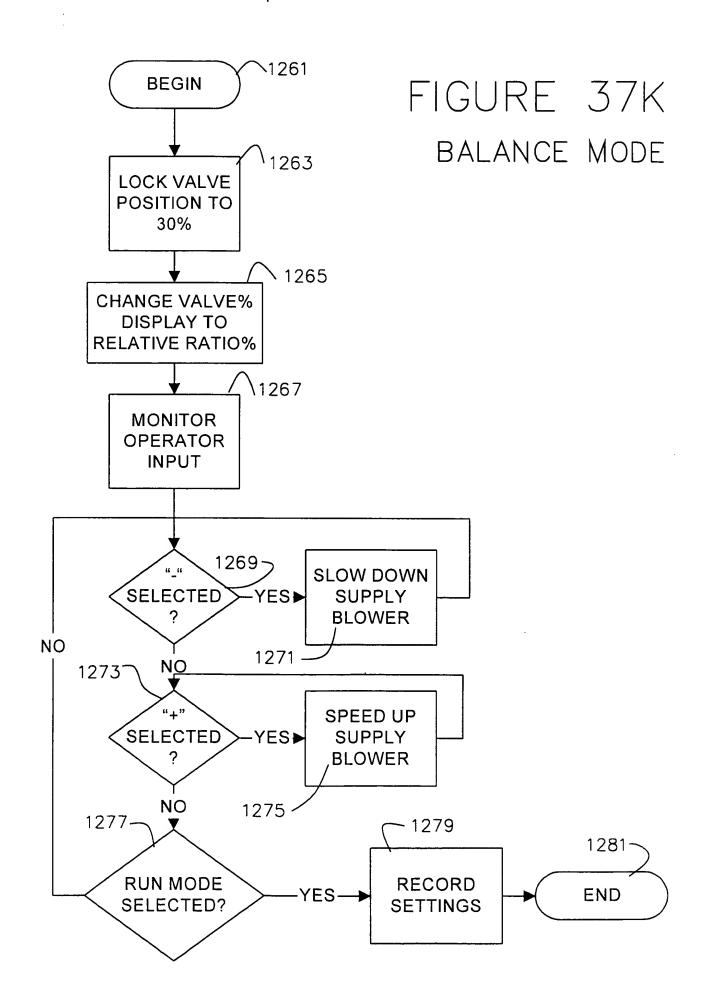






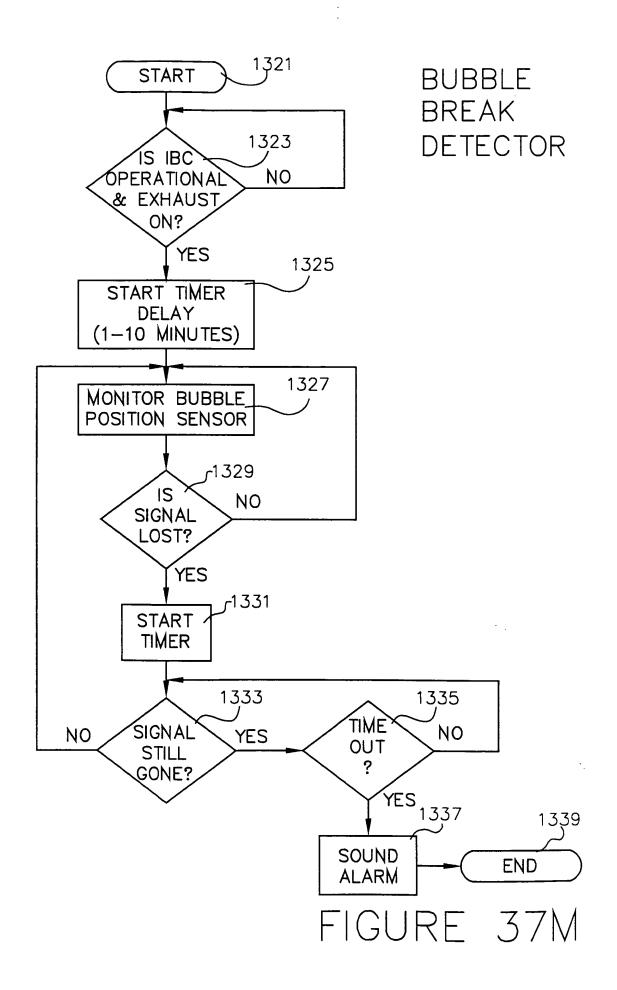


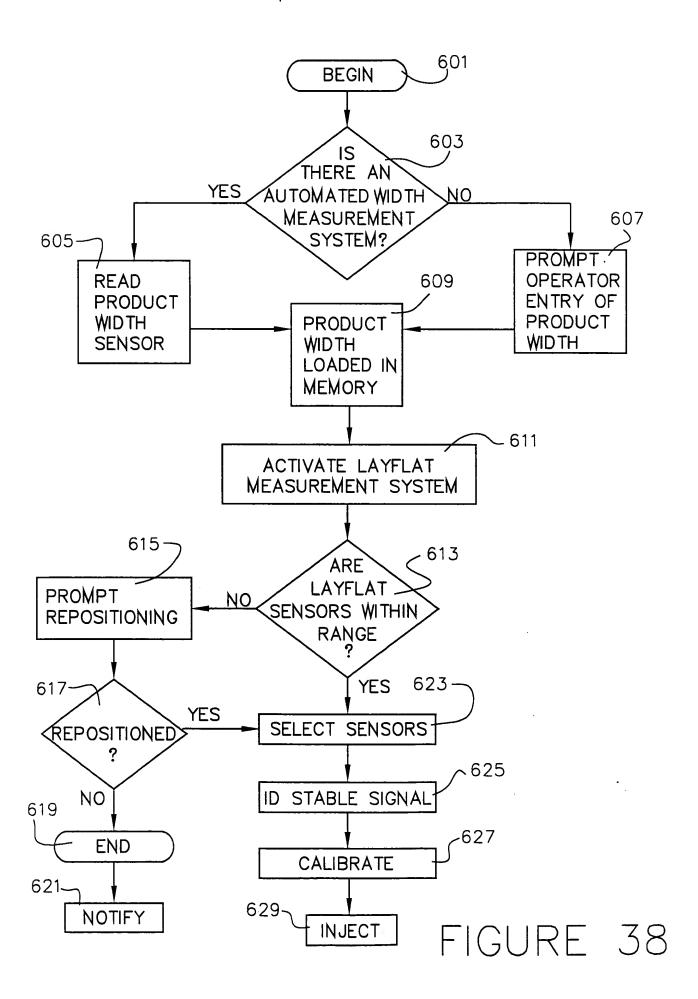


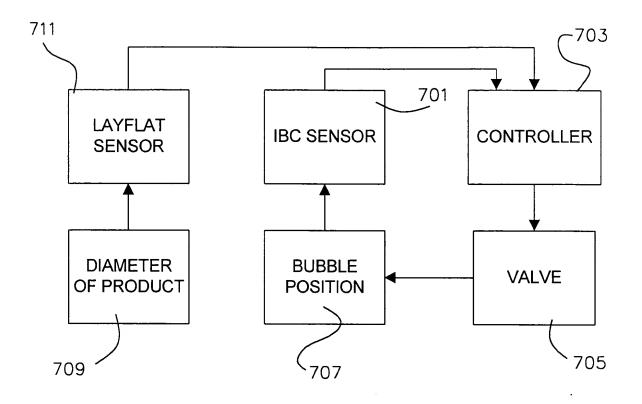


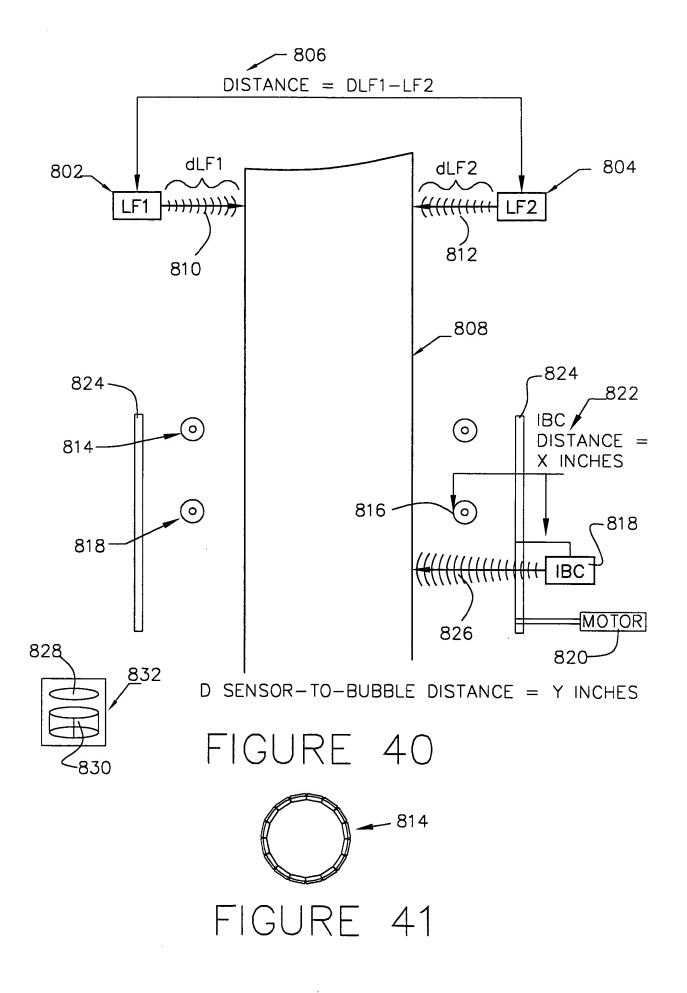
Replacement Sheet

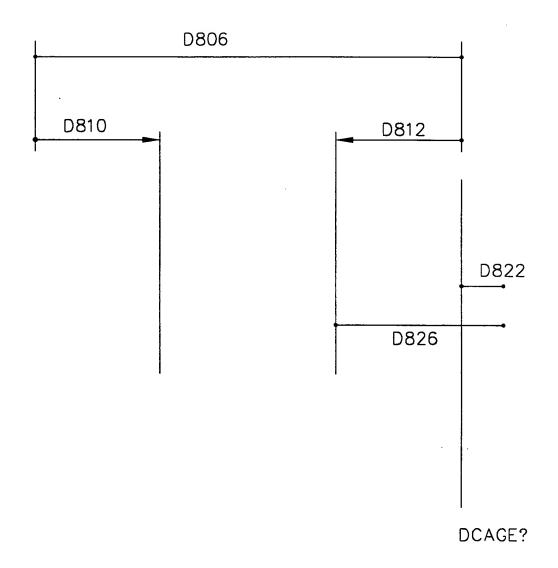
1301	1303	1305
MASTER SPEED POT SETTING	SUPPLY SPEED	REFERENCE VOLTS
A% B% • • •	CG · · · ·	BD BF · · · ·
Z%	AM	ВХ



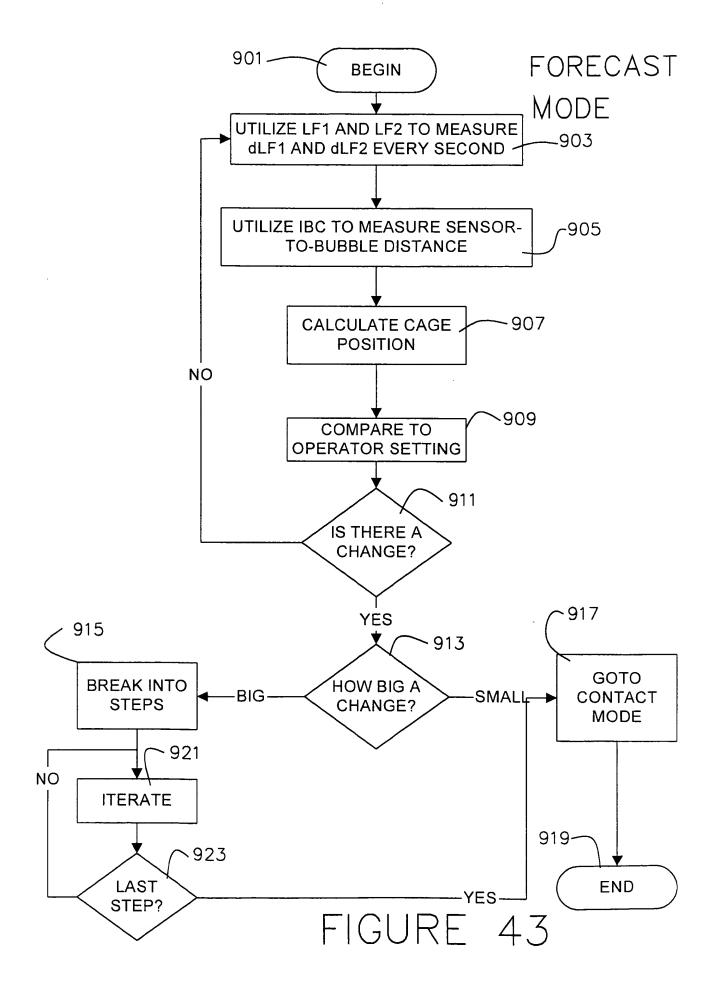


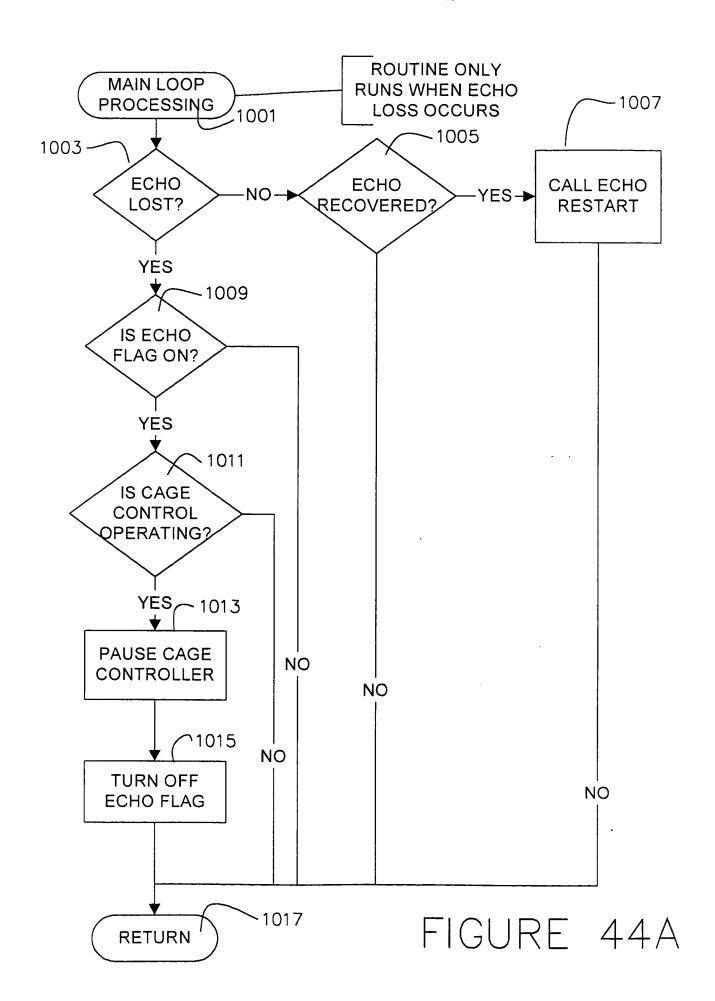


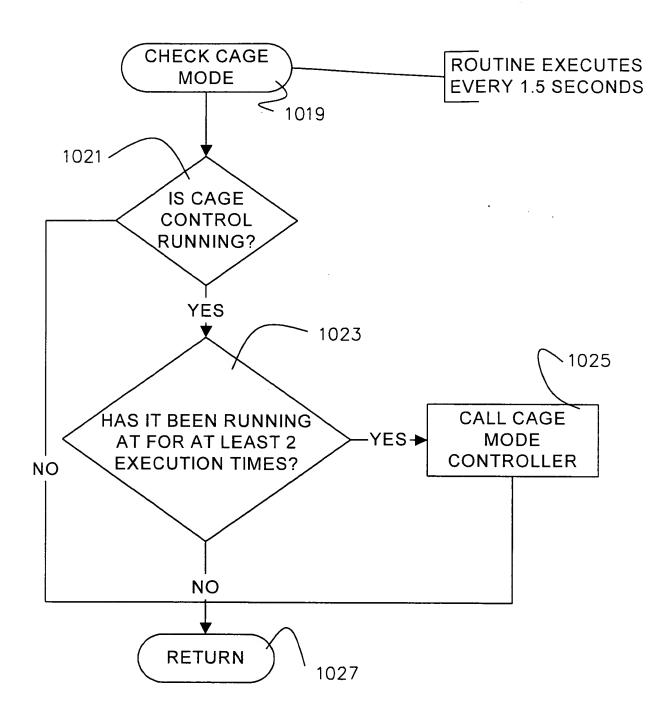


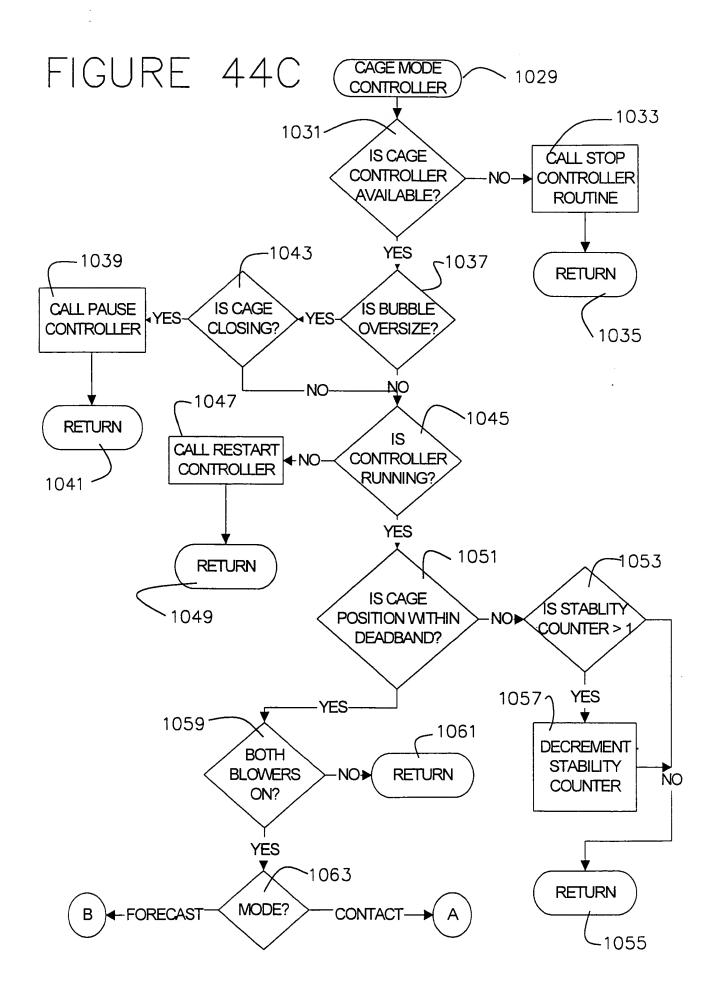


$$DCAGE = (D806 - D810 - D812) + (D826 - D822)$$



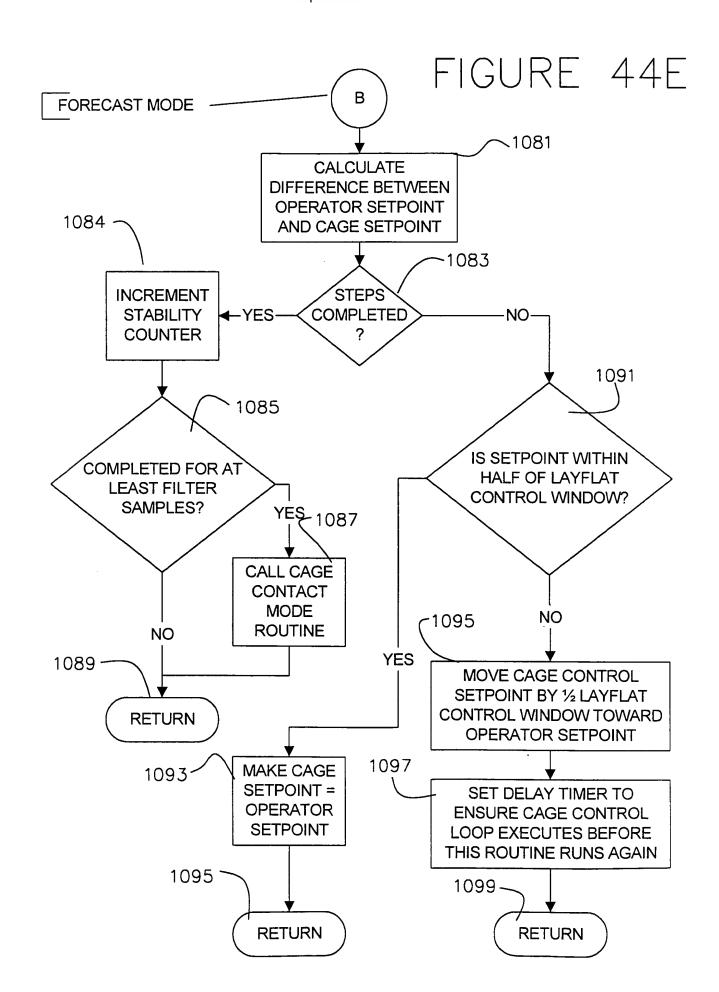






CONTACT MODE 1067-1065 IS LAYFLAT IS STABLITY **WITHIN** NO) COUNTER > 1? TOLERANCE? YES YES 1069 1073 **INCREMENT DECREMENT** STABLE OF STABLE NO **COUNT BY 1 COUNT BY 1** -1079 1075 **STOP** STABLE AT CONTACT **LEAST 5 PID RETURN ∢YES**-**MODE EXECUTIONS?** - 1071 **RETURN** 1077

FIGURE 44D



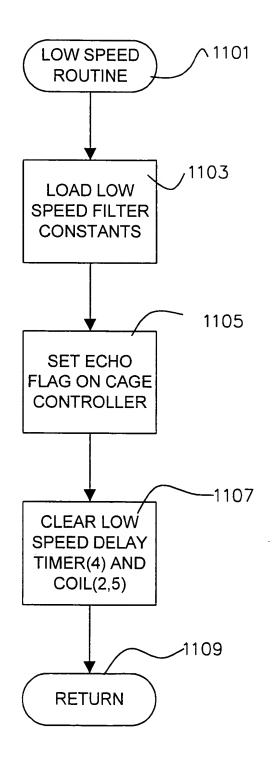


FIGURE 44F

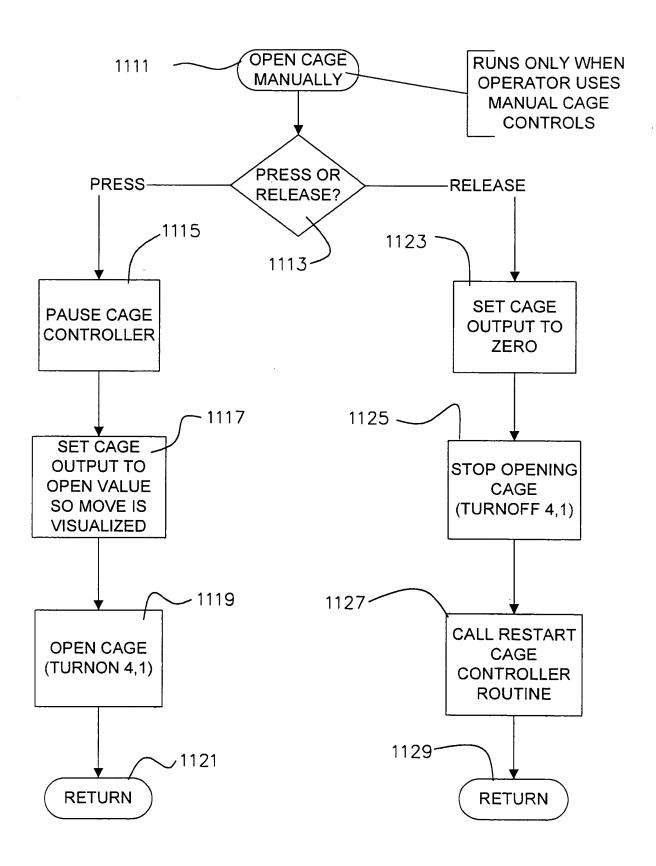


FIGURE 44G

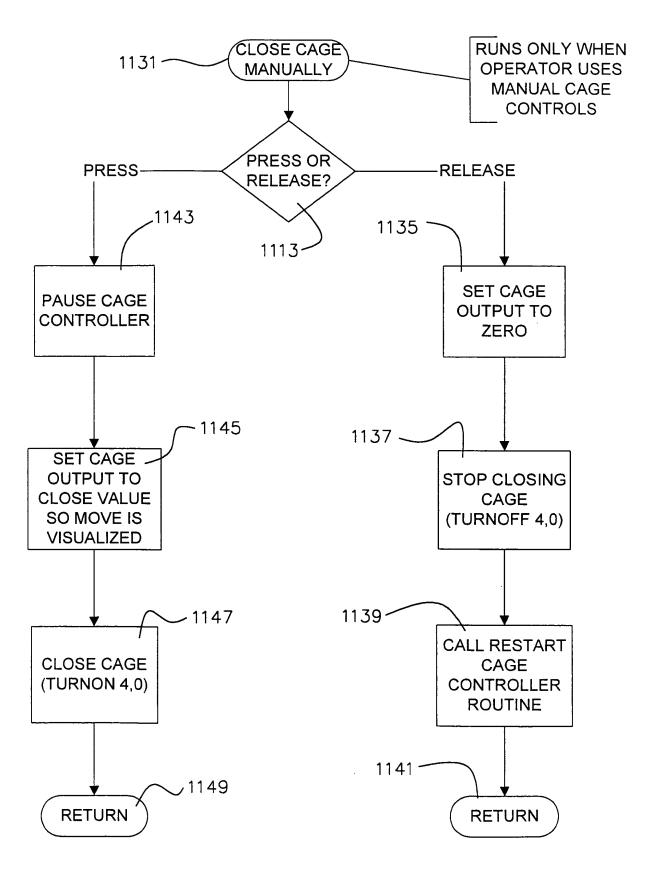


FIGURE 44G

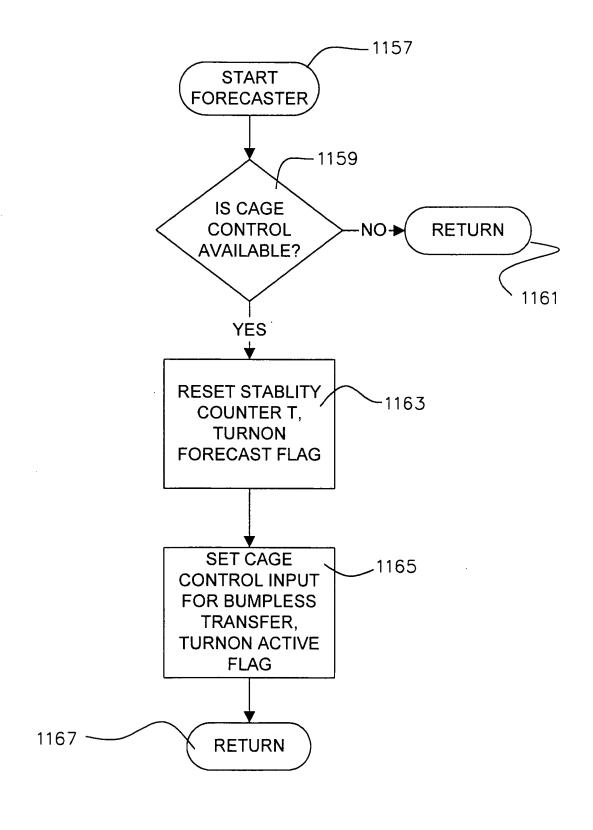
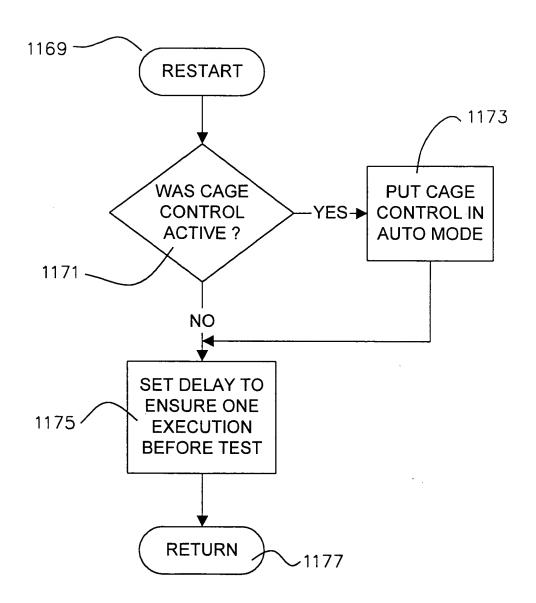


FIGURE 44J



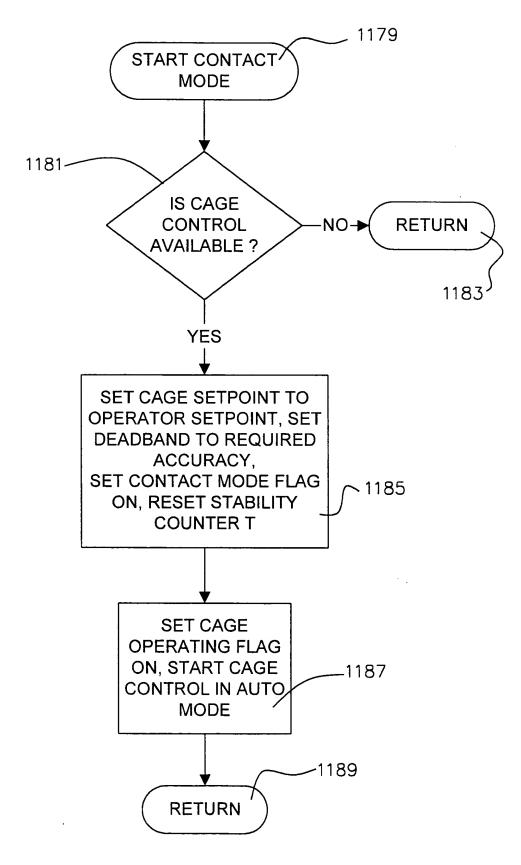
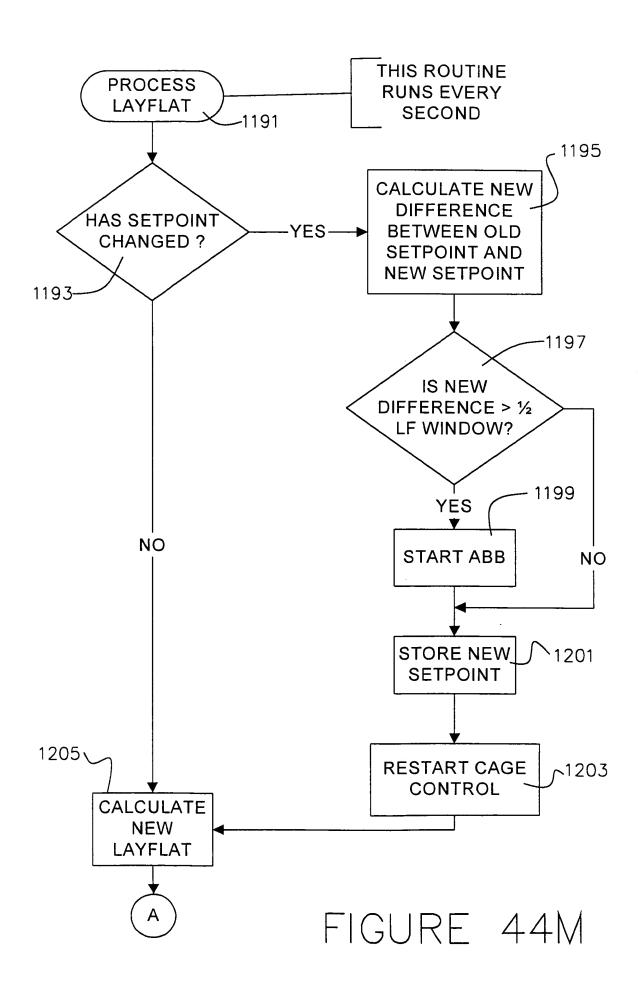


FIGURE 44L



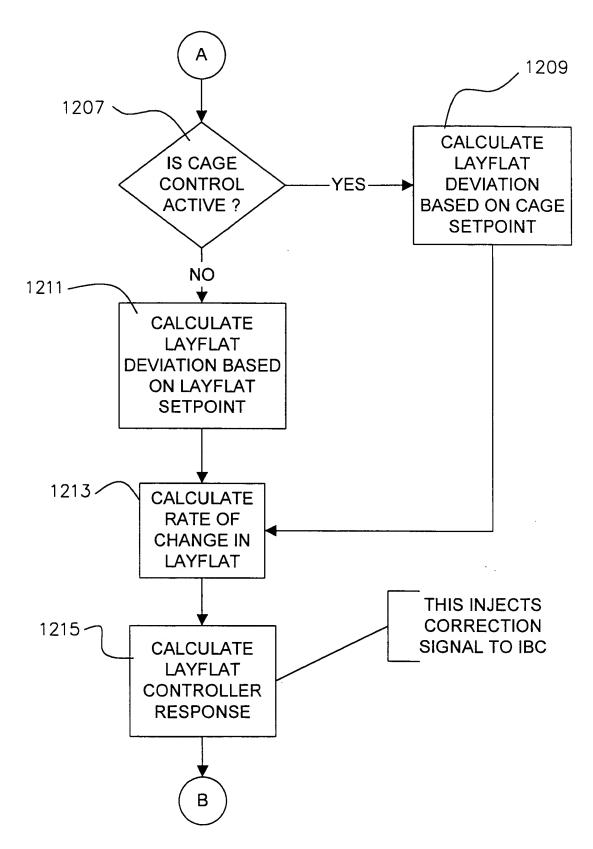
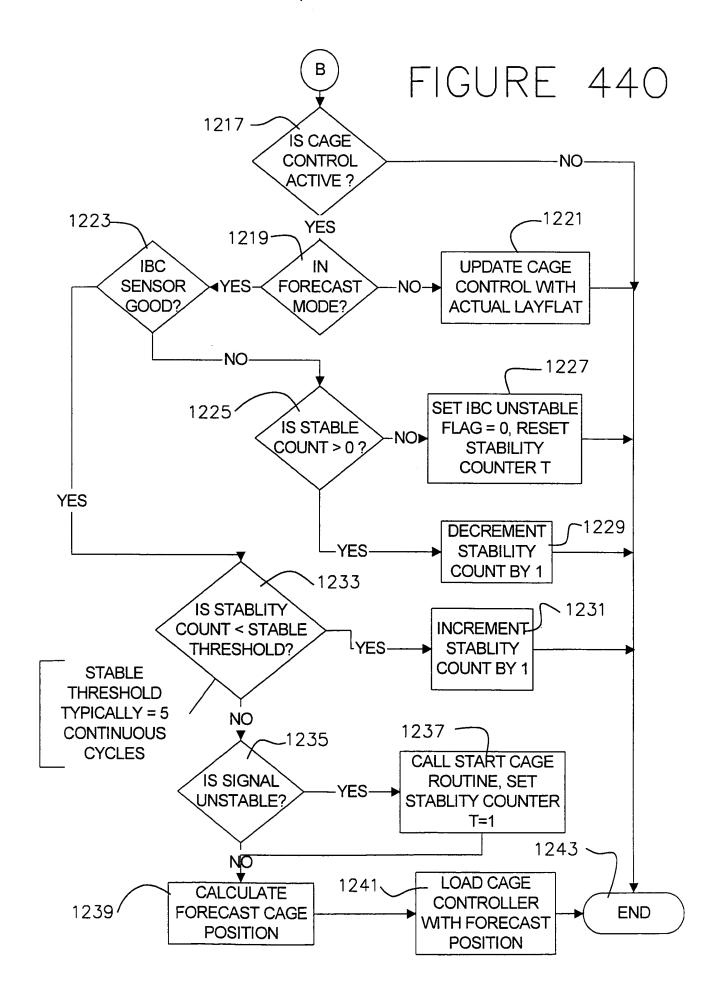


FIGURE 44N



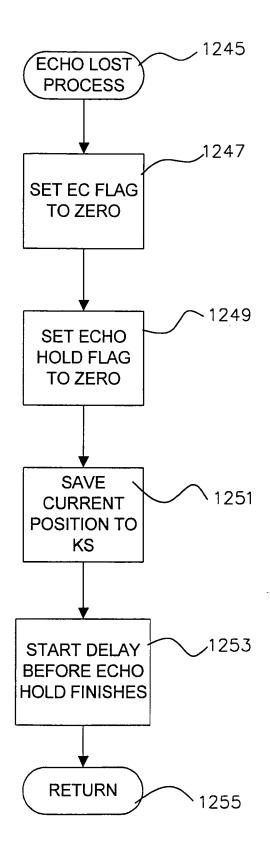


FIGURE 44P

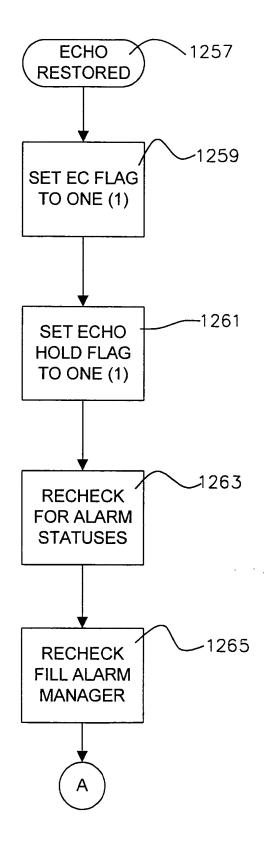
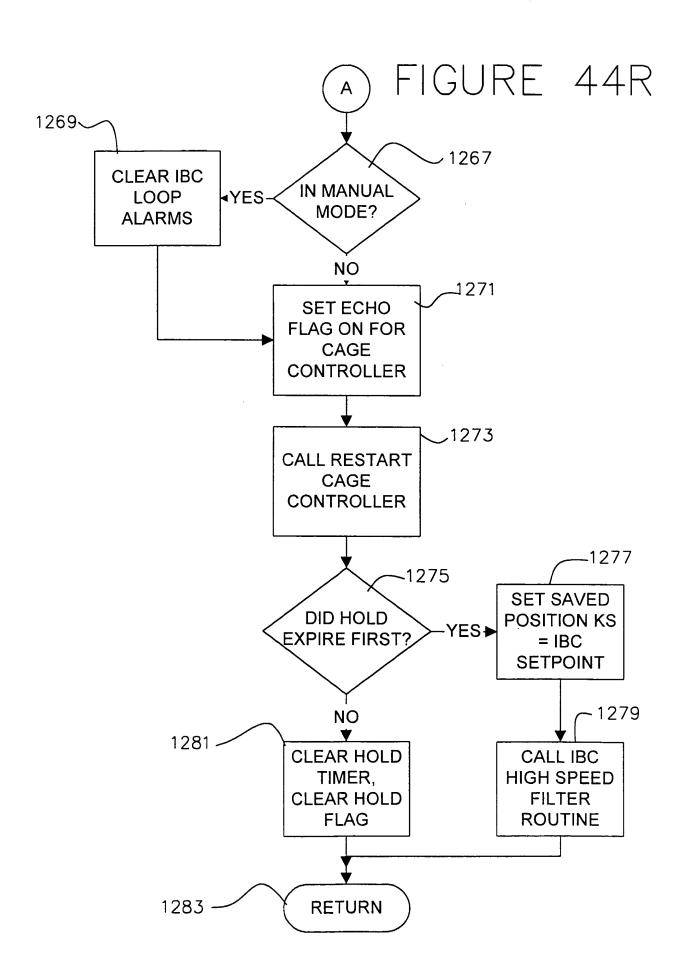


FIGURE 44Q



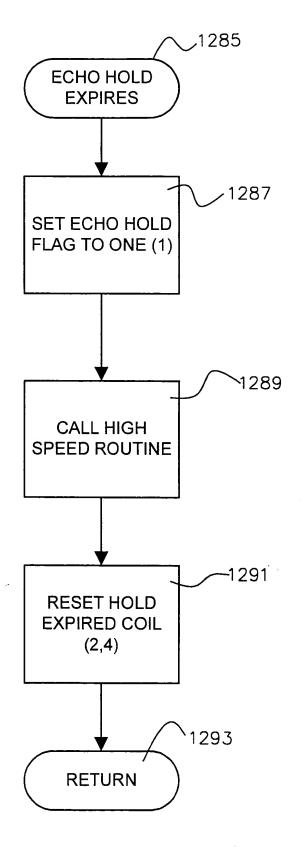
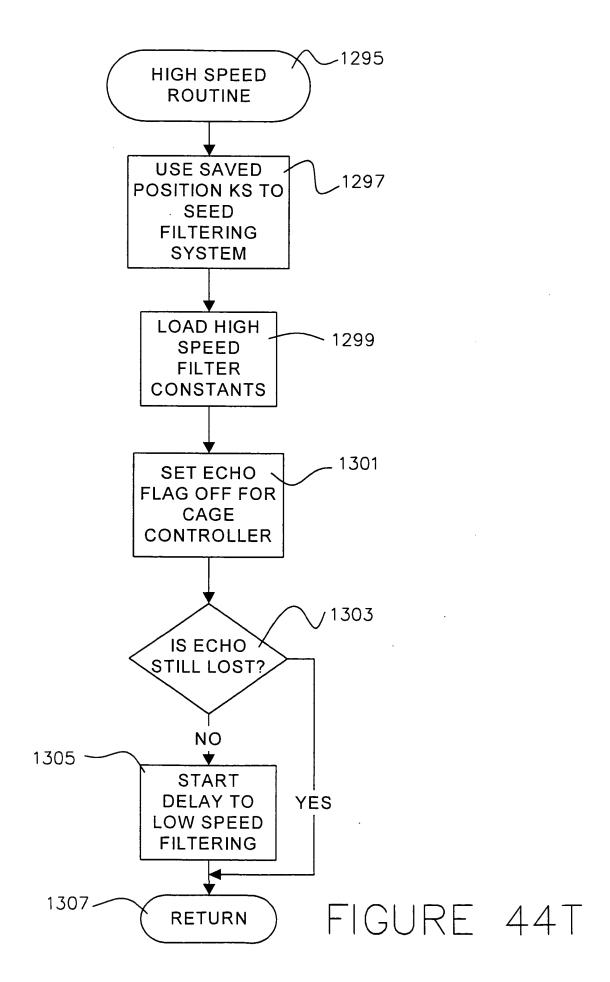


FIGURE 44S



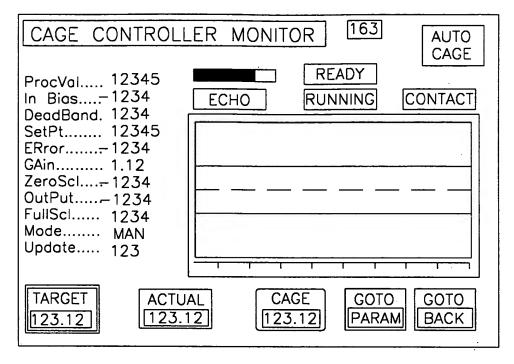


FIGURE 45

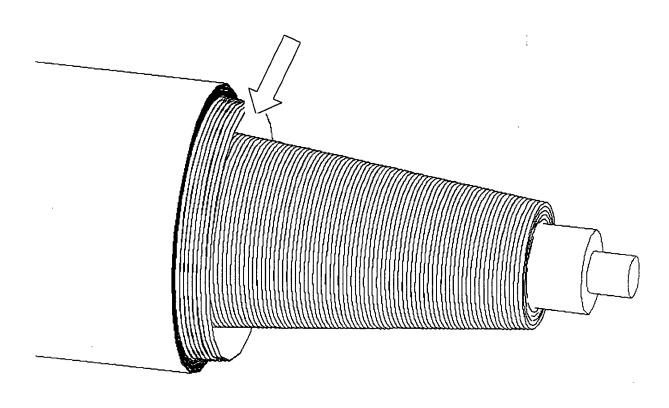


FIGURE 46

CAGE CONTROLLER PARAMETERS	ACCEPT
40 MIN P 45 OVRLM 48-CGSIZE 1.12 1.12	READY
41 UPDAT 46 CONCT 1.12	
42 ERROR 47 MAX P 1.12 1.1	
CAGE CONTROLLER PARAMETERS: TO GET HELP ON A PARAMETER, PRESS HELP AND ENTER THE NUMBER. PRESS ACCEPT TO LOAD NEW VALUES.	HELP GOTO BACK

FIGURE 47

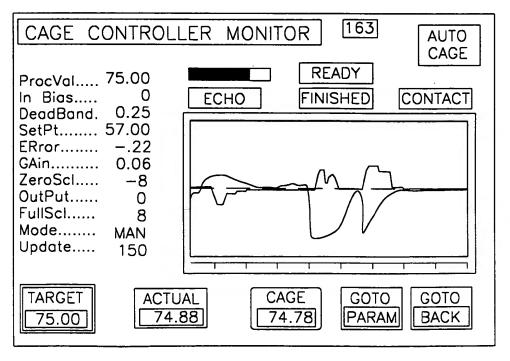


FIGURE 48

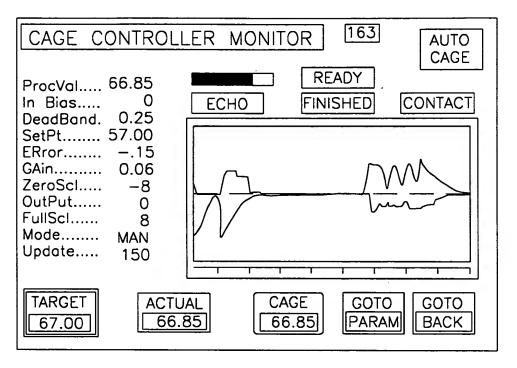


FIGURE 49

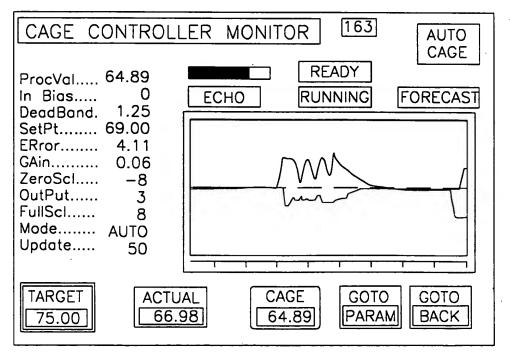


FIGURE 50

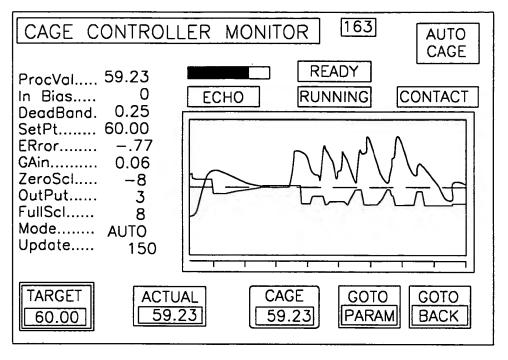


FIGURE 51

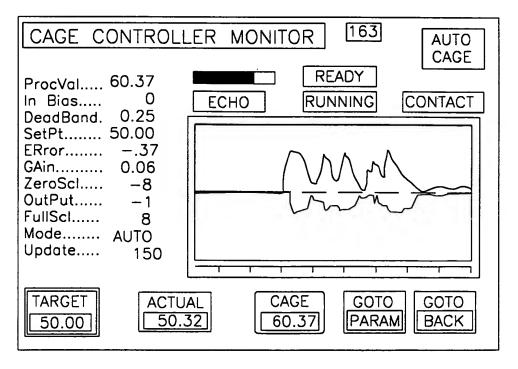


FIGURE 52

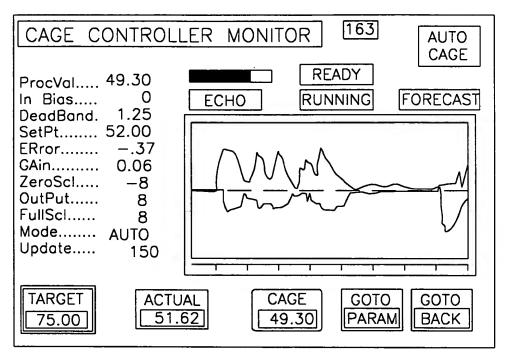


FIGURE 53